Contents

Introduction xxi

Chapter 1 Chemically Driven Artificial Molecular Machines
J.D. Crowley, E.R. Kay and D.A. Leigh

1.1 Design Principles for Molecular-Level Motors and Machines 1
  1.1.1 The Effects of Scale 2
  1.1.2 Machines that Operate at Low Reynolds Number 3
  1.1.3 Lessons to Learn from Biological Motors and Machines 3
1.2 Controlling Motion in Covalently Bonded Molecular Systems 4
  1.2.1 Controlling Conformational Changes 4
  1.2.2 Controlling Configurational Changes 9
1.3 Controlling Motion in Mechanically Bonded Molecular Systems 12
  1.3.1 Basic Features 13
  1.3.2 Translational Molecular Switches: Stimuli-Responsive Molecular Shuttles 13
  1.3.3 Controlling Rotational Motion in Catenanes 24
1.4 From Laboratory to Technology: Towards Useful Molecular Machines 29
  1.4.1 The Current Challenges: Constraining, Communicating, Correlating 30
  1.4.2 Reporting Controlled Motion in Solution 32
  1.4.3 Reporting Controlled Motion on Surfaces, in Solids and Other Condensed Phases 32
1.5 Summary and Outlook 38
References 40

Chapter 2 Photochemically Controlled Molecular Devices and Machines

V. Balzani, G. Bergamini, P. Ceroni, A. Credi and M. Venturi

2.1 Introduction 48
2.2 Molecular-level Devices for Processing Light Signals 50
  2.2.1 Wires 50
  2.2.2 Switching Devices 51
  2.2.3 Plug/socket Systems 52
  2.2.4 Molecular Extension Cables 53
  2.2.5 Antenna Systems for Light Harvesting 53
  2.2.6 Molecular Lenses Capable of Tuning the Colour of Light 56
  2.2.7 Fluorescent Sensors with Signal Amplification 56
  2.2.8 Dendrimers for a Multiple Use of Light Signals 59
  2.2.9 Logic Gates 62
2.3 Light-driven Molecular Machines 65
  2.3.1 Dethreading/rethreading of Pseudorotaxanes 65
  2.3.2 A Sunlight-Powered Nanomotor 66
2.4 Conclusions 69
Acknowledgements 70
References 70

Chapter 3 Transition-Metal Complex-Based Molecular Machines

B. Champin, U. Létinois-Halbes and J.-P. Sauvage

3.1 Introduction 76
3.2 Molecular Motions Driven by a Chemical Reaction 77
  3.2.1 Use of a Chemical Reaction to Induce the Contraction/Stretching Process of a Muscle-like Rotaxane Dimer 77
  3.2.2 Intramolecular Complexation/Decomplexation Processes as a Means to Make an Intermittent Degenerate Molecular Shuttle 78
  3.2.3 Molecular Machines Based on Metal-ion Translocation 82
3.3 Electrochemically Induced Motions 83
  3.3.1 Transition-metal-complexed Catenanes and Rotaxanes 83
  3.3.2 Other Related Noninterlocking Systems 89
3.4 Light-fuelled Molecular Machines 91
  3.4.1 Photoinduced Decoordination and Thermal Recoordination of a Ring in a Ruthenium(II)-containing 2catenane 91

3.4.2 A Photochemically Driven Molecular-level Abacus 92
3.5 Conclusion and Prospective 96
Acknowledgements 96
References 97

Chapter 4 Chemomechanical Polymers

H.-J. Schneider and K. Kato

4.1 Introduction 100
4.2 Chemomechanical Polymers Triggered by pH 101
4.3 Particle-size Effects and Kinetics 107
4.4 Water Uptake and Release 108
4.5 Concentration Profiles 110
4.6 Cooperativity and Logical Gate Functions 111
4.7 Selectivity with Organic Effector Molecules 114
4.8 Ternary Complex Formation for Amino Acids and Peptides as Effectors 117
4.9 Selectivity by Covalent Interactions/Glucose-triggered Size Changes 118
4.10 Conclusions 119
References 120

Chapter 5 Ionic Polymer Metal Nanocomposites as Intelligent Materials and Artificial Muscles

M. Shahinpoor

5.1 Summary 126
5.2 Introduction 127
5.3 Three-dimensional Fabrication of IPMNCs 128
5.4 Manfacturing Methodologies 128
5.5 Manufacturing Steps 129
5.6 Electrically Induced Robotic Actuation 130
5.7 Distributed Nanosensing and Transduction 132
5.8 Modeling and Simulation 136
5.9 Smart-Product Development 138
5.10 Medical, Engineering and Industrial Applications 139
References 140

Chapter 6 Artificial Muscles, Sensing and Multifunctionality

T.F. Otero

6.1 Introduction 142
6.2 Materials 143

6.3 Electrochemical Behaviour of Conducting Polymers in Aqueous Solution 143
6.4 Nonstoichiometric, Soft, and Wet Materials 147
6.5 Electrochemical Properties 149
  6.5.1 Electrochemomechanical Properties 150
  6.5.2 Electrochromic Properties 150
  6.5.3 Charge Storage 150
  6.5.4 Porosity 150
  6.5.5 Electron/Chemical Transduction 151
  6.5.6 Unparalleled Simultaneous Sensing Possibilities 151
6.6 Multifunctional and Biomimicking Properties 151
6.7 Natural Muscles 152
6.8 Devices based on the Electrochemical Properties of Conducting Polymers 153
  6.8.1 Artificial Muscles 153
  6.8.2 Other Electrochemically based Properties and Devices: Electrochromic Devices 170
  6.8.3 Batteries 172
  6.8.4 Membranes and Electron/Ion (or Electron/Chemical) Transducers 174
6.9 Theoretical Models 174
  6.9.1 Elastic Models 177
  6.9.2 Electrochemical Models 177
  6.9.3 Relaxation Models 178
  6.9.4 Molecular Dynamics Treatment 179
6.10 Final Remarks 179
References 182

Chapter 7 Electrochemically Controllable Polyacrylonitrile-Derived Artificial Muscle as an Intelligent Material
K.J. Kim and K. Choe

7.1 Polyacrylonitrile in General 191
7.2 Force-Strain Behaviour of Modified PAN 194
7.3 Actuation Properties of Modified PAN 194
  7.3.1 Length-change Characteristics of Modified PAN: Effect of pH Variation 194
  7.3.2 Generative Force Characteristics: pH-driven and/or Electrically Driven PAN Actuator 194
  7.3.3 Generative Force Characteristics: Effect of Different Anions 196
  7.3.4 Generative Force Characteristics: Effect of Acidity 197
7.4 Performance of PAN Bundle Artificial Muscle 198

7.4.1 Electric-current Effect on Force Generation 199
7.4.2 Work Performance 201
7.5 Summary of Performance Capability of PAN Artificial Muscle 201
References 203

Chapter 8 Unimolecular Electronic Devices

R.M. Metzger

8.1 Introduction 205
8.2 Donors and Acceptors; HOMOs and LUMOs 206
8.3 Contacts 207
8.4 Two-probe, Three-probe and Four-probe Electrical Measurements 209
8.5 Resistors 210
8.6 Rectifiers or Diodes 212
8.7 Switches 221
8.8 Capacitors 221
8.9 Future Flash Memories 222
8.10 Field Effect Transistors 222
8.11 Negative Differential Resistance Devices 222
8.12 Coulomb-blockade Device and Single-electron Transistor 222
8.13 Future Unimolecular Amplifiers 223
8.14 Future Organic Interconnects 223
Acknowledgements 223
References 223

Chapter 9 Piezoelectric Ceramics as Intelligent Multifunctional Materials

A. Yousefi-Koma

9.1 Introduction 231
9.2 Piezoelectricity 232
9.3 Piezoelectric Ceramics 232
9.4 Piezoelectric Ceramic Actuators 233
9.5 Modeling 235
9.5.1 Sensors 239
9.5.2 Actuators 242
9.6 Applications 242
9.6.1 Vibration/Acoustic Control 243
9.6.2 Rotor-blade Flap 245
9.6.3 Adaptive Structural Shape Control 246
9.6.4 Structural Health Monitoring 246
9.6.5 Compact Hybrid Actuators 247

9.7 Commercial Products 247
References 252

Chapter 10 Ferroelectric Relaxor Polymers as Intelligent Soft Actuators and Artificial Muscles
Q. M. Zhang, B. Chu and Z.-Y. Cheng

10.1 Introduction 256
10.2 High-energy Electron-irradiated Copolymer (HEEIP) 258
  10.2.1 Microstructures of HEEIP 258
  10.2.2 Electromechanical Responses of HEEIP 262
10.3 Electrostrictive Responses and Relaxor Ferroelectric Behaviour in P(VDF-TrFE)-based Terpolymers 266
  10.3.1 The Electromechanical Response in P(VDF-TrFE)-based Terpolymers 266
  10.3.2 The Microstructure and Ferroelectric Relaxor Behaviour of P(VDF-TrFE-CFE) Terpolymers 268
10.4 Performance of Microelectromechanical Devices 273
10.5 Summary 278
Acknowledgement 279
References 279

Chapter 11 Magnetic Polymeric Gels as Intelligent Artificial Muscles
M. Zrínyi

11.1 Introduction 282
11.2 Ferrogel as a New Type of Responsive Gel 283
11.3 Interpretation of the Abrupt Shape Transition 288
11.4 Nonhomogeneous Deformation of Ferrogels 290
11.5 Muscle-like Contraction Mimicked by Ferrogels 294
11.6 Control of Pseudomuscular Contraction 295
11.7 Future Aspects 299
Acknowledgements 299
References 299

Chapter 12 Intelligent Materials: Shape-Memory Polymers
M. Behl, R. Langer and A. Lendlein

12.1 Introduction 301
12.2 Thermally Induced Shape-memory Polymers 303
  12.2.1 General Concept and Characterisation of Shape-memory Effect 303

12.2.2 Thermoplastic Shape-memory Polymers 304
12.2.3 Covalently Crosslinked Shape-memory Polymers 306
12.2.4 Composites from Shape-memory Polymers and Particles 308
12.2.5 Indirect Actuation of Thermally Induced Shape-memory Effect in Polymers 308
12.3 Light-induced Shape-memory Polymers 311
12.4 Multifunctional Polymers with Shape-memory Effect 312
12.5 Conclusion and Outlook 313
References 314

Chapter 13 Shape-Memory Alloys as Multifunctional Materials
L. McDonald Schetky

13.1 Introduction to Shape-memory Alloys 317
13.2 Shape-memory Alloy Applications 320
13.2.1 Couplings 320
13.2.2 Seals 321
13.2.3 Electrical Connectors 322
13.2.4 Virtual Two-way Actuation Using One-way NiTi Shape-memory Alloys 323
13.2.5 Nonbiased Safety Devices 324
13.2.6 Thermal Interrupter 325
13.2.7 Eyeglass Frames 326
13.2.8 Cellular-phone Antennas 327
13.2.9 Home Appliances 327
13.3 Medical Applications 327
13.3.1 Orthodontics and Dental Procedures 328
13.3.2 Superelastic Medical Devices 328
13.3.3 Cardiovascular Stents 329
13.4 Engineering Applications 331
13.4.1 Adaptive Structures 331
13.4.2 Structural Damping 333
13.4.3 High-force Devices 334
13.4.4 Jet-engine and Other Aeronautical Applications 334
13.5 Thin-film and Porous Devices 336
References 338

Chapter 14 Magnetorheological Materials and their Applications
X. Wang and F. Gordaninejad

14.1 Introduction 339
14.2 Historical Perspective 340
14.3 Magnetorheological Materials 341

14.3.1 Magnetorheological Fluids 341
14.3.2 Magnetorheological Elastomers 344
14.3.3 Rheological Behaviour of MR Fluids 348
14.3.4 Models for Shear-yield Stress 351
14.3.5 Field-induced Microstructures 353
14.3.6 Rheometry of MR Fluids 354
14.3.7 Effects of Surface Roughness 357
14.4 Magnetorheological Fluid Devices 363
14.4.1 Magnetorheological Fluid Dampers 363
14.4.2 Modeling of Magnetorheological-Fluid Dampers 365
14.4.3 Effect of Temperature 369
14.4.4 Other Applications 373
14.5 Summary 376
Acknowledgements 376
References 376

Chapter 15 Metal Hydrides as Intelligent Materials and Artificial Muscles
K.J. Kim, G. Lloyd and M. Shahinpoor

15.1 Metal Hydrides in General 386
15.2 Metal-hydride-actuation Principle 387
15.2.1 Modeling 390
15.2.2 Experiments 393
15.3 Summary 394
References 394

Chapter 16 Dielectric Elastomer Actuators as Intelligent Materials for Actuation, Sensing and Generation
G. Kofod and R. Kornbluh

16.1 Introduction 396
16.2 Actuation Basics 397
16.3 Pre-stress Bias 399
16.4 Compliant Electrodes 400
16.4.1 Percolating Conductive Particle Networks 400
16.4.2 Structured Metal Electrodes 400
16.5 Theory and Modeling 401
16.6 Actuator Design: Geometry and Structure 405
16.7 Applications 406
16.7.1 Artificial Muscles for Biomimetic Robots 409
16.7.2 Linear Actuators for Industrial Applications 411
16.7.3 Diaphragm Actuators for Pumps and Arrays 411
16.7.4 Enhanced-thickness Mode Arrays 412

16.7.5 Framed Actuator for Optics 414
16.7.6 Sensors 415
16.7.7 Generators 416
16.8 Implementation Challenges for Dielectric Elastomers 417
16.9 The Future: Materials Development for New Elastomers 418
16.9.1 Improving Elastic Properties 419
16.9.2 Improving Dielectric Properties 420
16.9.3 Improving Breakdown Properties 420
16.10 Conclusion 421
References 421

Chapter 17 Azobenzene Polymers as Photomechanical and Multifunctional Smart Materials
K.G. Yager and C.J. Barrett

17.1 Introduction 424
17.2 Azobenzenes 425
17.3 Azobenzene Systems 427
17.4 Photoswitchable Azo Materials 430
17.5 Photoresponsive Azo Materials 432
17.5.1 Photo-orientation 432
17.5.2 Surface Properties 434
17.6 Photodeformable Azo Materials 434
17.6.1 Surface Mass Transport 434
17.6.2 Photomechanical Effects 437
17.7 Conclusion 437
References 438

Chapter 18 Intelligent Chitosan-based Hydrogels as Multifunctional Materials
A.F.T. Mak and S. Sun

18.1 Introduction 447
18.2 Characteristics of Chitosan 448
18.2.1 Physical and Chemical Properties of Chitosan 448
18.2.2 Biological Properties of Chitosan 449
18.2.3 Solvent and Solubility 449
18.3 Intelligent Properties 450
18.3.1 pH Sensitivity 450
18.3.2 Ionic Strength Sensitivity 452
18.3.3 Organic Effectors Sensitivity 453
18.3.4 Electrosensitivity 453
18.3.5 Thermosensitivity 455

18.4 Chitosan-based Intelligent Materials 456
18.4.1 pH-Responsive Hydrogels 456
18.4.2 Thermoresponsive and Dual Stimuli-responsive Polymers 456
18.4.3 Magnetic Chitosan Microsphere 457
18.4.4 Electrical Responsive Polymers 458
18.5 Biomedical Applications 458
18.5.1 Drug-delivery and Drug-release Systems 458
18.5.2 Injectable Gels for Tissue Engineering 460
18.5.3 Artificial Actuators and Muscles 460
18.6 Conclusions 461
References 461

Chapter 19 Polymer-Protein Complexation and its Application as ATP-driven Gel Machine
R. Kawamura, A. Kakugo, Y. Osada and J.P. Gong

19.1 Introduction 464
19.2 Actin Gel formed from Polymer–Actin Complexes 465
19.3 Polymorphism of Actin Complexes 467
19.4 Oriented Myosin Gel Formed under Shear Flow 469
19.5 Motility Assay of F-actin on Oriented Myosin Gel 470
19.6 Motility Assay of Polymer-Actin Complex Gel 471
19.7 Polarity of the Actin in Complexes 472
19.8 Conclusions 474
References 475

Chapter 20 Intelligent Composite Materials Having Capabilities of Sensing, Health Monitoring, Actuation, Self-Repair and Multifunctionality
H. Asanuma

20.1 Introduction 478
20.2 A New Route to Develop Intelligent Composite Materials 479
20.3 Composite Materials Fabricated by the New Route 481
20.4 A New Category of Composite Materials Having Liquid Phases for Self-repair and Other Capabilities 485
20.5 Summary and Outlook 489
References 490

Chapter 21 Overview of Liquid-crystal Elastomers, Magnetic Shape-memory Materials, Fullerenes, Carbon Nanotubes, Nonionic Smart Polymers and Electrorheological Fluids as Other Intelligent and Multifunctional Materials

M. Shahinpoor and H.-J. Schneider

21.1 Liquid-crystal Elastomers as Multifunctional Materials 491
21.2 Magnetic Shape-memory (MSM) Materials 493
  21.2.1 MSM Alloy Actuators 496
  21.2.2 Sensing and Multifunctionality Properties of MSM Materials 496
21.3 Fullerenes and Carbon Nanotubes as Multifunctional Intelligent Materials 497
21.4 Nonionic Polymer Gels/EAPs 500
21.5 Electrorheological (ER) Fluids as Multifunctional Smart Materials 500
  21.5.1 Other Applications of ER Fluids 501
References 501

Chapter 22 Overview on Biogenic and Bioinspired Intelligent Materials – from DNA-based Devices to Biochips and Drug-delivery Systems

H.-J. Schneider

22.1 Introduction 506
22.2 Biological Materials: Nucleic Acids as an Example 507
22.3 Biosensors and Biochips 508
22.4 Intelligent Bionanoparticles 509
22.5 Nanobiosensors 511
22.6 Drug-delivery and Related Systems 512
References 517

Subject Index 522