

## **SUPPORTING INFORMATION FOR:**

# **Renewable DNA Seesaw Logic Circuits Enabled by Photoregulation of Toehold-Mediated Strand Displacement**

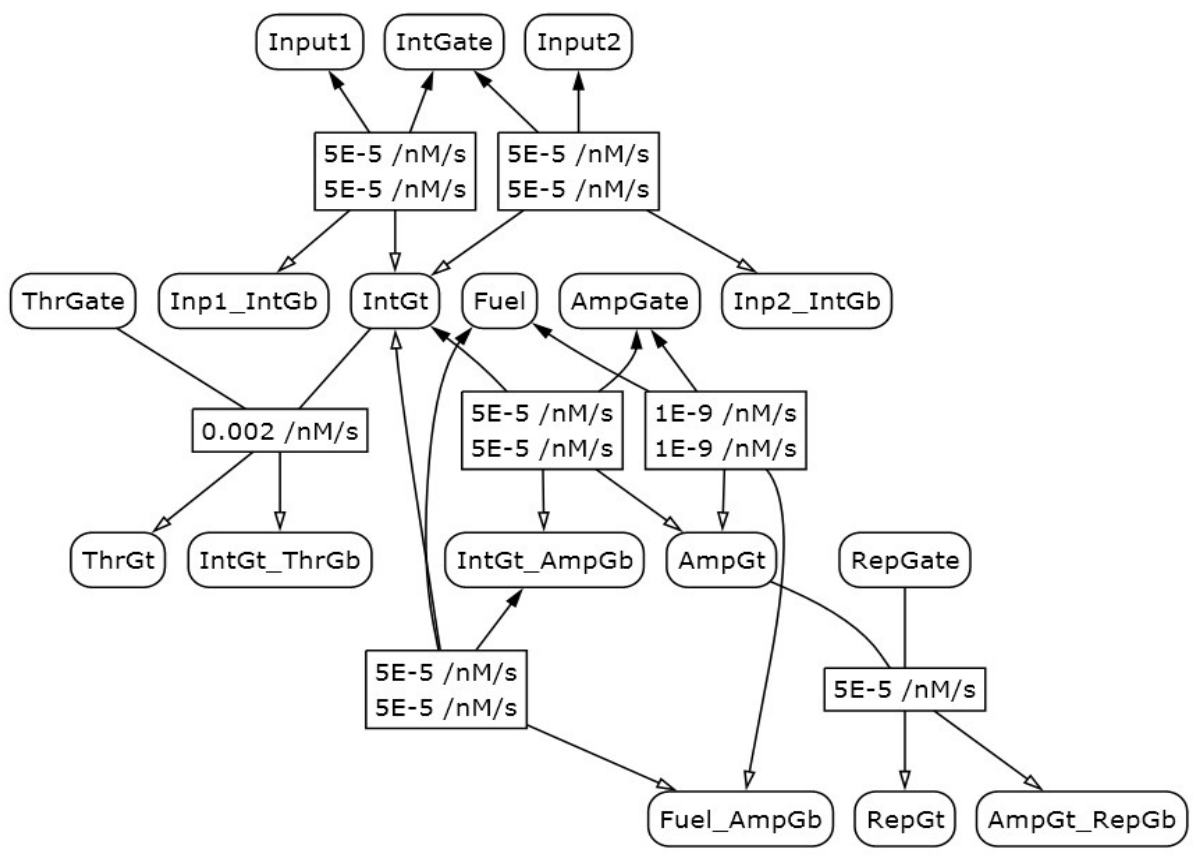
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**Figure S1.** Reaction graph of a DNA seesaw logic AND gate modified with trans-form azobenzenes.

Generated by Visual GEC.<sup>1</sup>

**Table S1.** Naming convention for reactants and products in the modeling

Species name	Meaning
Input1	ssDNA <b>input signal 1</b>
Input2	ssDNA <b>input signal 2</b>
IntGate	dsDNA integrating gate complex
ThrGate	dsDNA threshold gate complex
AmpGate	dsDNA amplifying gate complex
Fuel	ssDNA fuel strand
RepGate	dsDNA reporter gate complex
Inp1_IntGb	dsDNA complex formed by input signal 1 + integrating gate base strand
Inp2_IntGb	dsDNA complex formed by input signal 2 + integrating gate base strand
IntGt_ThrGb	dsDNA complex formed by integrating gate top strand + threshold gate base strand
IntGt_AmpGb	dsDNA complex formed by integrating gate top strand + amplifying gate base strand
Fuel_AmpGb	dsDNA complex formed by fuel strand + amplifying gate base strand
AmpGt_RepGb	dsDNA complex formed by amplifying gate top strand + reporter gate base strand
IntGt	ssDNA integrating gate top strand
ThrGt	ssDNA threshold gate top strand
AmpGt	ssDNA amplifying gate top strand
RepGt	ssDNA reporter gate top strand ( <b>regarded as gate output signal in our model</b> )

**Table S2.** BM rate constants for modeling DNA seesaw logic AND gate with trans-form azobenzenes

BM rate constant	Rate constant value (nM <sup>-1</sup> s <sup>-1</sup> )
ks	5e-05
kf	2e-03
kl	1e-09

**Table S3.** DNA species involved in the initial state of a seesaw logic AND gate

Species name	Initial concentration (nM)
Input1	90.0
Input2	90.0
IntGate	200.0
ThrGate	120.0
AmpGate	100.0
Fuel	200.0
RepGate	150.0

**Table S4.** Final state of seesaw AND gate forward operation under different Boolean input combinations

DNA species	Final conc. (nM) Input: ON-ON	Final conc. (nM) Input: ON-OFF	Final conc. (nM) Input: OFF-ON	Final conc. (nM) Input: OFF-OFF
Input1	17.7	0.1	0	0
Input2	17.7	0	0.1	0
IntGate	55.5	100.1	100.1	180
ThrGate	0	20.1	20.1	100
AmpGate	0.3	95.6	95.6	99.5
Fuel	111.2	195.6	195.6	199.5
RepGate	50.4	145.6	145.6	149.5
Inp1_IntGb	72.3	89.9	10	10
Inp2_IntGb	72.3	10	89.9	10
IntGt_ThrGb	120	99.9	99.9	20
IntGt_AmpGb	10.9	0	0	0
Fuel_AmpGb	88.8	4.4	4.4	0.5
AmpGt_RepGb	99.6	4.4	4.4	0.5
IntGt	13.6	0	0	0
ThrGt	120	99.9	99.9	20
AmpGt	0.1	0	0	0
RepGt	99.6 (Output ON)	4.4 (Output OFF)	4.4 (Output OFF)	0.5 (Output OFF)

**Table S5.** Estimation of ksc and the corresponding critical concentration

Invading toehold length n (nt)	Invading toehold binding energy (kcal/mol) <sup>2</sup>	MATLAB command	MB rate constant ksc = k <sub>{5,n}</sub> (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
0	+1.9	BM_rate([1.9,-6.7,15,25,3])	4.1410e-10	3.2839e+08
1	+0.2	BM_rate([0.2,-6.7,15,25,3])	7.2793e-09	1.8681e+07
2	-1.7	BM_rate([-1.7,-6.7,15,25,3])	1.7928e-07	7.5853e+05
3	-3.0	BM_rate([-3.0,-6.7,15,25,3])	1.6047e-06	8.4743e+04
4	-4.7	BM_rate([-4.7,-6.7,15,25,3])	2.7996e-05	4.8574e+03
5	-6.9	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S6.** Estimation of krc and the corresponding critical concentration

Incumbent toehold length m (nt)	Incumbent toehold binding energy (kcal/mol) <sup>2</sup>	MATLAB command	MB rate constant krc = k <sub>{m,5}</sub> (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
0	+1.2	BM_rate([-6.9,1.2,15,25,3])	0.0011	168.7599
1	-0.6	BM_rate([-6.9,-0.6,15,25,3])	0.0011	168.7594
2	-2.7	BM_rate([-6.9,-2.7,15,25,3])	0.0011	168.7415
3	-4.5	BM_rate([-6.9,-4.5,15,25,3])	0.0010	168.3806
4	-5.6	BM_rate([-6.9,-5.6,15,25,3])	0.0010	166.4296
5	-6.7	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S7.** Estimation of tksc and the corresponding critical concentration

Temporary incumbent toehold length m (nt)	Invading toehold length n (nt) $n = 10 * \left(1 - \frac{m}{5}\right)$	Effective length of branch migration domain b (nt) $b = 15 - m$	MATLAB command	MB rate constant tksc = k <sub>{m,n}</sub> (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
5	0	10	BM_rate([1.9,-6.7,10,25,3])	5.5582e-10	4.9259e+08
4	2	11	BM_rate([-1.7,-5.6,11,25,3])	2.9992e-07	1.0344e+06
3	4	12	BM_rate([-4.7,-4.5,12,25,3])	4.5100e-05	6.1018e+03
2	6	13	BM_rate([-8.3,-2.7,13,25,3])	0.0029	80.4382
1	8	14	BM_rate([-11.9,-0.6,14,25,3])	0.0035	58.3359
0	10	15	BM_rate([-14.8,1.2,15,25,3])	0.0035	50.7938

**Table S8.** Estimation of tkrc and the corresponding critical concentration

Invading toehold length n (nt)	Incumbent toehold length m (nt)	Effective length of branch migration domain b (nt) $b = 15 - n$	MATLAB command	MB rate constant tkrc = k <sub>{m,n}</sub> (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
5	0	10	BM_rate([-6.9,1.2,10,25,3])	0.0014	291.2350
4	2	11	BM_rate([-4.7,-2.7,11,25,3])	4.9574e-05	6.6652e+03
3	4	12	BM_rate([-3,-5.6,12,25,3])	2.4730e-06	1.0595e+05
2	6	13	BM_rate([-1.7,-9.5,13,25,3])	6.6223e-09	8.7519e+05

**Table S9.** Estimation of rpks and the corresponding critical concentration

Invading toehold length n (nt)	Incumbent toehold length m (nt) $m = 5 - n$	Effective length of branch migration domain b (nt) $b = 15 - m$	MATLAB command	MB rate constant rpks = k <sub>{m,n}</sub> (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
0	5	10	BM_rate([1.9,-6.7,10,25,3])	5.5582e-10	4.9259e+08
1	4	11	BM_rate([0.2,-5.6,11,25,3])	1.2178e-08	2.5475e+07
2	3	12	BM_rate([-1.7,-4.5,12,25,3])	2.9022e-07	9.4820e+05
3	2	13	BM_rate([-3,-2.7,13,25,3])	2.4190e-06	9.7803e+04
4	1	14	BM_rate([-4.7,-0.6,14,25,3])	3.9088e-05	5.2210e+03
5	0	15	BM_rate([-6.9,1.2,15,25,3])	0.0011	168.7599

**Table S10.** Estimation of rpkrc and the corresponding critical concentration

Invading toehold length $n$ (nt)	Incumbent toehold length $m$ (nt) $m = 5 - n$	Effective length of branch migration domain $b$ (nt) $b = 15 - n$	MATLAB command	MB rate constant rpkrc = $k_{\{m,n\}}$ ( $\text{nM}^{-1}\text{s}^{-1}$ )	Critical concentration (nM)
5	0	10	BM_rate([-6.9,1.2,10,25,3])	0.0014	291.2350
4	1	11	BM_rate([-4.7,-0.6,11,25,3])	4.9597e-05	6.6652e+03
3	2	12	BM_rate([-3,-2.7,12,25,3])	2.6204e-06	1.0596e+05
2	3	13	BM_rate([-1.7,-4.5,13,25,3])	2.6809e-07	8.7525e+05
1	4	14	BM_rate([0.2,-5.6,14,25,3])	9.6965e-09	2.0016e+07
0	5	15	BM_rate([1.9,-6.7,15,25,3])	4.1410e-10	3.2839e+08

**Table S11.** Estimation of ampksc and the corresponding critical concentration

Invading toehold length $n$ (nt)	Effective length of branch migration domain $b$ (nt)	Incumbent toehold length $m$ (nt) $m = 20 - b$	MATLAB command	MB rate constant ampksc = $k_{\{m,n\}}$ ( $\text{nM}^{-1}\text{s}^{-1}$ )	Critical concentration (nM)
0	10	10	N/A	N/A	N/A
1	11	9	N/A	N/A	N/A
2	12	8	N/A	N/A	N/A
3	13	7	BM_rate([-3,-10.2,13,25,3])	1.8529e-08	9.7736e+04
4	14	6	BM_rate([-4.7,-9.5,14,25,3])	1.0402e-06	5.1643e+03
5	15	5	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S12.** Estimation of ampkrc and the corresponding critical concentration

Invading toehold length $n$ (nt) $n = 20 - b$	Effective length of branch migration domain $b$ (nt)	Incumbent toehold length $m$ (nt)	MATLAB command	MB rate constant ampkrc = $k_{\{m,n\}}$ ( $\text{nM}^{-1}\text{s}^{-1}$ )	Critical concentration (nM)
10	10	0	BM_rate([-14.8,1.2,10,25,3])	0.0035	114.2859
9	11	1	BM_rate([-12.9,-0.6,11,25,3])	0.0035	94.4561
8	12	2	BM_rate([-11.9,-2.7,12,25,3])	0.0035	79.3614
7	13	3	BM_rate([-9.2,-4.5,13,25,3])	0.0034	69.8579
6	14	4	BM_rate([-8.3,-5.6,14,25,3])	0.0029	67.3766
5	15	5	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S13.** Estimation of fksc and the corresponding critical concentration

Invading toehold length $n$ (nt)	Effective length of branch migration domain $b$ (nt)	Incumbent toehold length $m$ (nt)	MATLAB command	MB rate constant fksc = $k_{\{m,5\}}$ ( $\text{nM}^{-1}\text{s}^{-1}$ )	Critical concentration (nM)
5	10	0	BM_rate([-6.9,1.2,10,25,3])	0.0014	291.2350
5	11	1	BM_rate([-6.9,-0.6,11,25,3])	0.0013	255.3127
5	12	2	BM_rate([-6.9,-2.7,12,25,3])	0.0012	226.7870
5	13	3	BM_rate([-6.9,-4.5,13,25,3])	0.0012	203.1576
5	14	4	BM_rate([-6.9,-5.6,14,25,3])	0.0011	181.8446
5	15	5	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S14.** Estimation of fkrc and the corresponding critical concentration

Invading toehold length n (nt)	Effective length of branch migration domain b (nt)	Incumbent toehold length m (nt)	MATLAB command	MB rate constant fkrc = $k_{\{5,n\}}$ (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
0	10	5	BM_rate([1.9,-6.7,10,25,3])	5.5582e-10	4.9259e+08
1	11	5	BM_rate([0.2,-6.7,11,25,3])	9.1446e-09	2.5475e+07
2	12	5	BM_rate([-1.7,-6.7,12,25,3])	2.1165e-07	9.4817e+05
3	13	5	BM_rate([-3,-6.7,13,25,3])	1.7869e-06	9.7785e+04
4	14	5	BM_rate([-4.7,-6.7,14,25,3])	2.9487e-05	5.2066e+03
5	15	5	BM_rate([-6.9,-6.7,15,25,3])	8.6716e-04	156.8197

**Table S15.** Estimation of ampfkrc and the corresponding critical concentration

Invading toehold length n (nt)	Effective length of branch migration domain b (nt)	Incumbent toehold length m (nt)	MATLAB command	MB rate constant ampfkrc = $k_{\{0,n\}}$ (nM <sup>-1</sup> s <sup>-1</sup> )	Critical concentration (nM)
5	15	0	BM_rate([-6.9,1.2,15,25,3])	0.0011	168.7599
4	15	0	BM_rate([-4.7,1.2,15,25,3])	3.6510e-05	4.8693e+03
3	15	0	BM_rate([-3,1.2,15,25,3])	2.0976e-06	8.4755e+04
2	15	0	BM_rate([-1.7,1.2,15,25,3])	2.3437e-07	7.5854e+05
1	15	0	BM_rate([0.2,1.2,15,25,3])	9.5163e-09	1.8681e+07
0	15	0	BM_rate([1.9,1.2,15,25,3])	5.4136e-10	3.2839e+08

**Text S1:** ODE Modeling of the Mass-Action Kinetics of Seesaw Logic AND Gate Forward Operation. Generated by Dynetica.<sup>3</sup>

$$\begin{aligned}
 d[\text{Input1}]/dt &= -1.0 * (k_s * [\text{Input1}] * [\text{IntGate}]) + k_s * [\text{Inp1\_IntGb}] * [\text{IntGt}] \\
 d[\text{Input2}]/dt &= -1.0 * (k_s * [\text{Input2}] * [\text{IntGate}]) + k_s * [\text{Inp2\_IntGb}] * [\text{IntGt}] \\
 d[\text{IntGate}]/dt &= (-1.0 * (k_s * [\text{Input1}] * [\text{IntGate}]) + k_s * [\text{Inp1\_IntGb}] * [\text{IntGt}]) - k_s * [\text{Input2}] * [\text{IntGate}] + k_s * [\text{Inp2\_IntGb}] * [\text{IntGt}] \\
 d[\text{ThrGate}]/dt &= -1.0 * (k_f * [\text{IntGt}] * [\text{ThrGate}]) \\
 d[\text{AmpGate}]/dt &= (-1.0 * (k_s * [\text{IntGt}] * [\text{AmpGate}]) + k_s * [\text{IntGt\_AmpGb}] * [\text{AmpGt}]) - k_l * [\text{AmpGate}] * [\text{Fuel}] + k_l * [\text{Fuel\_AmpGb}] * [\text{AmpGt}] \\
 d[\text{Fuel}]/dt &= (-1.0 * (k_s * [\text{IntGt\_AmpGb}] * [\text{Fuel}]) + k_s * [\text{Fuel\_AmpGb}] * [\text{IntGt}]) - k_l * [\text{AmpGate}] * [\text{Fuel}] + k_l * [\text{Fuel\_AmpGb}] * [\text{AmpGt}] \\
 d[\text{RepGate}]/dt &= -1.0 * (k_s * [\text{AmpGt}] * [\text{RepGate}]) \\
 d[\text{Inp1\_IntGb}]/dt &= k_s * [\text{Input1}] * [\text{IntGate}] - k_s * [\text{Inp1\_IntGb}] * [\text{IntGt}] \\
 d[\text{Inp2\_IntGb}]/dt &= k_s * [\text{Input2}] * [\text{IntGate}] - k_s * [\text{Inp2\_IntGb}] * [\text{IntGt}] \\
 d[\text{IntGt\_ThrGb}]/dt &= k_f * [\text{IntGt}] * [\text{ThrGate}] \\
 d[\text{IntGt\_AmpGb}]/dt &= k_s * [\text{IntGt}] * [\text{AmpGate}] - k_s * [\text{IntGt\_AmpGb}] * [\text{AmpGt}] - k_s * [\text{IntGt\_AmpGb}] * [\text{Fuel}] + k_s * [\text{Fuel\_AmpGb}] * [\text{IntGt}] \\
 d[\text{Fuel\_AmpGb}]/dt &= (k_s * [\text{IntGt\_AmpGb}] * [\text{Fuel}] - k_s * [\text{Fuel\_AmpGb}] * [\text{IntGt}]) + k_l * [\text{AmpGate}] * [\text{Fuel}] - k_l * [\text{Fuel\_AmpGb}] * [\text{AmpGt}] \\
 d[\text{AmpGt\_RepGb}]/dt &= k_s * [\text{AmpGt}] * [\text{RepGate}] \\
 d[\text{IntGt}]/dt &= (((k_s * [\text{Input1}] * [\text{IntGate}] - k_s * [\text{Inp1\_IntGb}] * [\text{IntGt}] + k_s * [\text{Input2}] * [\text{IntGate}]) - k_s * [\text{Inp2\_IntGb}] * [\text{IntGt}] - k_s * [\text{IntGt}] * [\text{AmpGate}] + k_s * [\text{IntGt\_AmpGb}] * [\text{AmpGt}]) - k_f * [\text{IntGt}] * [\text{ThrGate}] + k_s * [\text{IntGt\_AmpGb}] * [\text{Fuel}]) - k_s * [\text{Fuel\_AmpGb}] * [\text{IntGt}] \\
 d[\text{ThrGt}]/dt &= k_f * [\text{IntGt}] * [\text{ThrGate}]
 \end{aligned}$$

$$d[\text{AmpGt}]/dt = (k_s * [\text{IntGt}] * [\text{AmpGate}] - k_s * [\text{IntGt\_AmpGb}] * [\text{AmpGt}] - k_s * [\text{AmpGt}] * [\text{RepGate}] + k_l * [\text{AmpGate}] * [\text{Fuel}] - k_l * [\text{Fuel\_AmpGb}] * [\text{AmpGt}])$$

$$d[\text{RepGt}]/dt = k_s * [\text{AmpGt}] * [\text{RepGate}]$$

Parameter values:

```
-----
ks = 0.00005
kf = 0.002
kl = 0.000000001
```

**Text S2:** MATLAB Code (with Modifications on Units of Numerical Values) for Estimating BM Rate Constants Associated with Seesaw Gate Renewal Process. Complete MATLAB script was adapted from the Supporting Information of Prior Publication by Zhang and Winfree.<sup>2</sup>

```
%BM rate constant (in unit of nM-1s-1)
BM_rate = 1E-9 * kf * kb * incumbent_offrate / (invading_offrate * incumbent_offrate
...
+ kb * invading_offrate + kb * incumbent_offrate)

%critical concentration (in unit of nM)
c_crit = 1E9 * (0.1 / kf) * (invading_offrate * incumbent_offrate + kb *
invading_offrate ...
+ kb * incumbent_offrate) / (incumbent_offrate + kb)

output = [BM_rate, c_crit];
```

**Text S3:** LBS Program for Simulating the Mass-Action Kinetics of a Seesaw Logic AND Gate Functionalized with Cis-Form Azobenzenes.

```
////////////////////////////////////
// LBS code for seesaw gate renewal process
// Gate type: AND
// Input combination: ON, ON
// Effective azobenzene isomerization yield: 80%
////////////////////////////////////
```

```
directive sample 36000.0 2000
```

```
rate ksc = 7.2793e-09;
rate krc = 0.0011;
rate tksc = 2.9992e-07;
rate tkrc = 4.9574e-05;
rate rpksc = 1.2178e-08;
rate rpkrc = 4.9597e-05;
rate ampksc = 0;
rate ampkrc = 0.0035;
rate fksc = 0.0013;
rate fkrc = 9.1446e-09;
rate ampfksc = 0;
rate ampfkrc = 3.6510e-05;
```

```
spec Input1 = new Input1;
```

```

spec Input2 = new Input2;
spec RepGt = new RepGt;

init Input1 17.7 |
init Input2 17.7 |

module gateAND(spec Input1, Input2){

    spec IntGate = new IntGate;
    spec ThrGate = new ThrGate;
    spec AmpGate = new AmpGate;
    spec Fuel = new Fuel;
    spec RepGate = new RepGate;
    spec Inp1_IntGb = new Inp1_IntGb;
    spec Inp2_IntGb = new Inp2_IntGb;
    spec IntGt_ThrGb = new IntGt_ThrGb;
    spec IntGt_AmpGb = new IntGt_AmpGb;
    spec Fuel_AmpGb = new Fuel_AmpGb;
    spec AmpGt_RepGb = new AmpGt_RepGb;
    spec IntGt = new IntGt;
    spec ThrGt = new ThrGt;
    spec AmpGt = new AmpGt;

    init IntGate      55.5   | // integrating gate
    init ThrGate      0      | // threshold gate
    init AmpGate      0.3    | // amplifying gate
    init Fuel         111.2  | // Fuel
    init RepGate      50.4   | // reporter gate

    init Inp1_IntGb   72.3   | // input 1 + integrating gate bottom
    init Inp2_IntGb   72.3   | // input 2 + integrating gate bottom
    init IntGt_ThrGb  120    | // integrating top + threshold gate bottom
    init IntGt_AmpGb  10.9   | // integrating top + amplifying gate bottom
    init Fuel_AmpGb   88.8   | // Fuel + amplifying gate bottom
    init AmpGt_RepGb  99.6   | // amplifying gate top + reporter gate bottom

    init IntGt        13.6   | // integrating gate top
    init ThrGt        120    | // threshold gate top
    init AmpGt        0.1    | // amplifying gate top
    init RepGt        99.6   | // reporter gate top

    // regeneration of integrating gate and inputs
    Input1 + IntGate <->{ksc}{krc} Inp1_IntGb + IntGt |
    Input2 + IntGate <->{ksc}{krc} Inp2_IntGb + IntGt |

    // regeneration of threshold gate
    IntGt + ThrGate <->{tksc}{tkrc} IntGt_ThrGb + ThrGt |

    // regeneration of reporter gate
    AmpGt + RepGate <->{rpks}{rpkrc} AmpGt_RepGb + RepGt |

    // regeneration of amplifying gate and fuel
    IntGt + AmpGate <->{ampksc}{ampkrc} IntGt_AmpGb + AmpGt |
    IntGt_AmpGb + Fuel <->{fksc}{fkrc} Fuel_AmpGb + IntGt |
    Fuel + AmpGate <->{ampfksc}{ampfkrc} Fuel_AmpGb + AmpGt |

};

```



gateAND(Input1, Input2)

## REFERENCES

- 1 M. Pedersen and A. Phillips, *J. R. Soc. Interface R. Soc.*, 2009, **6**, S437–S450.
- 2 D. Y. Zhang and E. Winfree, *J. Am. Chem. Soc.*, 2009, **131**, 17303–17314.
- 3 L. You, A. Hoonlor and J. Yin, *Bioinformatics*, 2003, **19**, 435–436.