# A numerical model for charge transport and 

# energy conversion of perovskite solar cells-SI 

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## Numerical solution process details

## Adapted equations and boundary conditions

The specific method we used to solve our equations are the relaxation method for 'Two Point Boundary Value Problems' in Numerical Recipes in Fortran. ${ }^{1}$ Here, for convenience, we repeat these five first differential equations:

$$
\begin{array}{lr}
J_{p}=-e D_{p} \frac{\partial p}{\partial x}+e p \mu_{p} F ; & J_{n}=e D_{n} \frac{\partial n}{\partial x}+e n \mu_{n} F \\
\frac{\partial J_{n}}{\partial x}=-e G+e R ; & \frac{\partial J_{p}}{\partial x}=e G-e R  \tag{1}\\
\frac{\partial F}{\partial x}=e \frac{p-n}{\varepsilon \varepsilon_{0}} &
\end{array}
$$

and five boundary conductions:

$$
\begin{array}{ll}
\left.J_{n}\right|_{x=d}=0 ; & \left.J_{p}\right|_{x=0}=0 ; \\
F_{x=d}=F_{d} ; & \left.\left.n\right|_{x=0} p\right|_{x=d}=N_{c} N_{v} e^{\frac{E_{b g a p}-V}{-k T}} \tag{2}
\end{array}
$$

If we want to use the "Two point Boundary Value Problems" method in Numerical Recipes in Fortran, ${ }^{1}$ all of the equation must be the first order differential and the boundary condition at two point is not coupled. While, the last boundary condition in Equation 2 is coupled. To decouple we add a new function $n^{0}(x)=\left.n\right|_{x=0}$, which is the electron density at $\mathrm{x}=0$. It is a constant. To simplify, we set $J_{n}=J_{n} / e, J_{p}=J_{/} e, n=n e$ and $p=p e$. We rewrite Equations 1 in the form used in Numerical Recipes in Fortran $\left(\frac{\partial y}{\partial x}=g(x, y)\right)$ :

$$
\begin{align*}
\frac{\partial p}{\partial x} & =\left(p \mu_{p} F-J_{p}\right) / D_{p} ; & \frac{\partial n}{\partial x}=\left(J_{n}-n \mu_{n} F\right) / D_{n} \\
\frac{\partial J_{n}}{\partial x} & =-G+R ; & \frac{\partial J_{p}}{\partial x}=G-R  \tag{3}\\
\frac{\partial F}{\partial x} & =\frac{p-n}{\varepsilon \varepsilon_{0}} ; & \frac{\partial n^{0}}{\partial x}=0
\end{align*}
$$

and boundary conditions:

$$
\begin{array}{lll}
\left.J_{p}\right|_{x=0}=0 ; & \left.F\right|_{x=0}=F_{0} ; & \left.n\right|_{x=0}=\left.n^{0}\right|_{x=0} \\
\left.F\right|_{x=d}=F_{d} ; & \left.J_{n}\right|_{x=d}=0 ; & \left.p\right|_{x=d}=\frac{N_{c} N_{v}}{\left.n^{0}\right|_{x=d}} e^{\frac{E_{b g a p}-V}{-k T}} \tag{4}
\end{array}
$$

To implement these six (total number of equations, noted as $N$ in Numerical recipes) equations into Fortran code, differential Equations 3 are approximated by finite-difference equations (FDEs) on a grid of points (total point number, noted as $M$ in Numerical recipes, we will discuss it in section Mesh test) that spans whole perovskite layer:

$$
\begin{align*}
& n^{0}(k)-n^{0}(k-1)=0 \\
& J_{p}(k)-J_{p}(k-1)-h(G-R)=0 \\
& F(k)-F(k-1)-h\left(\frac{\frac{p(k)+p(k-1)}{2}-\frac{n(k)+n(k-1)}{2}}{\varepsilon \varepsilon_{0}}\right)=0 \\
& n(k)-n(k-1)-h\left(\frac{J_{n}(k)+J_{n}(k-1)}{2 D_{n}}-\frac{\mu_{n}}{D_{n}} \frac{n(k)+n(k-1)}{2} \frac{F(k)+F(k-1)}{2}\right)=0  \tag{5}\\
& p(k)-p(k-1)-h\left(\frac{\mu_{p}}{D_{p}} \frac{p(k)+p(k-1)}{2} \frac{F(k)+F(k-1)}{2}-\frac{J_{p}(k)+J_{p}(k-1)}{2 D_{p}}\right)=0 \\
& J_{n}(k)-J_{n}(k-1)-h(-G+R)=0
\end{align*}
$$

where $h=x(k)-x(k-1)$. Then the problem becomes FDEs on a mesh of $M$ points, a solution consists of values for $N$ dependent functions given at each of the $M$ mesh points, or $N \times M$ variables in all. The method determines the solution by starting with a guess and improving it, iteratively. As the iterations improve the solution, the result is said to relax to the true solution.

## General procedures

To simplify illustration, we set all these parameters as: $y_{1}=n^{0} ; y_{2}=J_{p} ; y_{3}=F ; y_{4}=$ $n ; y_{5}=p ; y_{6}=J_{n}$. We use the notation $\mathbf{y}_{k}$ to refer the entire set of dependent variables $y_{1}$, $y_{2}, \ldots, y_{6}$ at point $x_{k}$, and use the notation $\mathbf{g}_{k}$ to refer all the functions. Then Equation 5
can be written:

$$
\begin{equation*}
0=\mathbf{E}_{k} \equiv \mathbf{y}_{k}-\mathbf{y}_{k-1}-\left(x_{k}-x_{k-1}\right) \mathbf{g}_{k}\left(x_{k}, x_{k-1}, \mathbf{y}_{k}, \mathbf{y}_{k-1}\right) \tag{6}
\end{equation*}
$$

Where $\mathbf{E}_{k}$ is the errors of guessed solution. Equation 6 provides six equations coupling twelve variables at point $k, k-1$. There are $M-1$ points, $k=2,3, \ldots, M$. Thus, Equation 6 provides a total of $(M-1) N$ equations for $6 M$ unknowns. The remaining six equations come from boundary conditions.

At the first boundary $(x=0)$, we have 3 conditions (first three in Equation 4)

$$
\begin{equation*}
0=\mathbf{E}_{1} \equiv \mathbf{B}\left(\mathbf{x}_{1}, \mathbf{y}_{1}\right) \tag{7}
\end{equation*}
$$

while at the second boundary $(x=d$, last three in Equation 4)

$$
\begin{equation*}
0=\mathbf{E}_{M+1} \equiv \mathbf{C}\left(\mathbf{x}_{M}, \mathbf{y}_{M}\right) \tag{8}
\end{equation*}
$$

The solution of Equation 6, 7 and 8 consist of the six variables $y_{j}$ at the $M$ points $x_{k}$. We give a initial guess (we will give it later), then corrections was applied to approximating to the solution. The correction are developed by expanding the FDEs in first-order Taylor series with respect to small changes $\Delta \mathbf{y}$. At an interior point $(2<k<M)$, this gives:

$$
\begin{equation*}
\mathbf{E}_{k}\left(\mathbf{y}_{k}+\Delta \mathbf{y}_{k}, \mathbf{y}_{k-1}+\Delta \mathbf{y}_{k-1}\right) \approx \mathbf{E}_{k}\left(\mathbf{y}_{k}, \mathbf{y}_{k-1}\right)+\sum_{i=1}^{N} \frac{\partial \mathbf{E}_{k}}{\partial y_{i, k-1}} \Delta y_{i, k-1}+\sum_{i=1}^{N} \frac{\partial \mathbf{E}_{k}}{\partial y_{i, k}} \Delta y_{i, k} \tag{9}
\end{equation*}
$$

To approach a solution, $\mathbf{E}(\mathbf{y}+\Delta \mathbf{y})$ should be updated to be zero. The general set of equations at an interior point can be written in matrix form as

$$
\begin{equation*}
\sum_{i=1}^{6} S_{j, i} \Delta y_{i, k-1}+\sum_{i=6+1}^{12} S_{j, i} \Delta y_{i-6, k}=-E_{j, k}, \quad j=1,2, \ldots 6 \tag{10}
\end{equation*}
$$

where, $S_{j, i}=\frac{\partial \mathbf{E}_{k}}{\partial y_{i, k-1}}, S_{j, i+6}=\frac{\partial \mathbf{E}_{k}}{\partial y_{i, k}}$. The dimension of $S_{j, i}$ is $6 \times 12$ at each $k$.

Figure 1: Matrix structure of a set of linear six FDEs with three boundary conditions imposed at both endpoints. One X represents a coefficient of the FDEs, V represents a component of the unknown solution vector, and B is a component of the known right-hand side. Empty spaces represent zeros.

Similarly, the algebraic relations at the boundaries can be expanded in a first-order Taylor series for increments that improve the solution. Since $\mathbf{E}_{1}$ depends only on $\mathbf{y}_{1}$, we find at the first boundary:

$$
\begin{equation*}
\sum_{i=1}^{6} S_{j, i} \Delta y_{i, 1}=-E_{j, 1}, \quad j=4,5,6 \tag{11}
\end{equation*}
$$

where $S_{j, i}=\frac{\partial E_{j, 1}}{\partial y_{n, 1}}$. At the second boundary,

$$
\begin{equation*}
\sum_{i=1}^{6} S_{j, i} \Delta y_{i, M}=-E_{j, M+1}, \quad j=1,2,3 \tag{12}
\end{equation*}
$$

where $S_{j, i}=\frac{\partial E_{j, M+1}}{\partial y_{n, M}}$.
We thus have in Equations 10, 11 and 12 a set of linear equations to be solved for the correction $\Delta \mathbf{y}$, iterating until the corrections are sufficiently small. The equations have a
special structure, because each $S_{j, i}$ couples only points $k, k-1$. Figure 1 shows the structure of the complete matrix equation for the case of $M=3$. There are 3 boundary conditions at the first and at the second boundary. The block boxed by red lines at left-up corner comes from the boundary condition $S_{j, i}$ at point $k=1$. Next two are the $S_{j, i}$ from $k=2$ and $k=3$. The last block is corresponding to the 3 second boundary conditions. This special form matrix is diagonalizated by splitting into it $M$ small matrix, and then diagonalizate the matrix from the first point $k=1$ to the last points $k=M+1$. For more details, please check Numerical recipes.

## S matrix

S matrix varies for different models. Here, we use direct recombination model ( $R=r \times n \times p$, Equation 12 in main text) as an example. For SRH model and other models, the $S_{j, i}$ at each $k$ points can be obtained by its definition in Equation 6, 7 and 8. To simplify illustration, we set all these parameters as: $y_{1}=n^{0} ; y_{2}=J_{p} ; y_{3}=F ; y_{4}=n ; y_{5}=p ; y_{6}=J_{n}$. Here, we only shows non-zero element. $h$ is the size of discretion, $h=x(k)-x(k-1)=\frac{d}{M}$. We substitute $\mu$ with Einstein relation $\mu=\frac{e D}{k T}=\frac{D}{0.026}$ and $R$ with rnp. Equation 5 can be rewritten:

$$
\begin{align*}
& y_{1}(k)-y_{1}(k-1) \equiv E_{1}=0 \\
& y_{2}(k)-y_{2}(k-1)-h\left(G-r \frac{y_{5}(k)+y_{5}(k-1)}{2} \frac{y_{4}(k)+y_{4}(k-1)}{2}\right) \equiv E_{2}=0 \\
& y_{3}(k)-y_{3}(k-1)-h\left(\frac{\frac{y_{5}(k)+y_{5}(k-1)}{2}-\frac{y_{4}(k)+y_{4}(k-1)}{2}}{\varepsilon \varepsilon_{0}}\right) \equiv E_{3}=0 \\
& y_{4}(k)-y_{4}(k-1)-h\left(\frac{y_{6}(k)+y_{6}(k-1)}{2 D_{p}}-\frac{\mu_{p}}{D_{p}} \frac{y_{4}(k)+y_{4}(k-1)}{2} \frac{y_{3}(k)+y_{3}(k-1)}{2}\right) \equiv E_{4}=0 \\
& y_{5}(k)-y_{5}(k-1)-h\left(-\frac{y_{2}(k)+y_{2}(k-1)}{2 D_{n}}+\frac{\mu_{n}}{D_{n}} \frac{y_{5}(k)+y_{5}(k-1)}{2} \frac{y_{3}(k)+y_{3}(k-1)}{2}\right) \equiv E_{5}=0 \\
& y_{6}(k)-y_{6}(k-1)-h\left(-G+r \frac{y_{5}(k)+y_{5}(k-1)}{2} \frac{y_{4}(k)+y_{4}(k-1)}{2}\right) \equiv E_{6}=0 \tag{13}
\end{align*}
$$

For convenience's sake, we define $\operatorname{tmp} 1=y(4, k)+y(4, k-1) ; \operatorname{tmp} 2=y(5, k)+y(5, k-$ $1) ; t m p=t m p 1+t m p 2$. The S matrix is shown below written in Fortran. Here, LT is the recombination coefficient $r$, ne is six (the number if equation, noted as $N$ in Numerical recipes $). \mathrm{S}(\mathrm{i}, \mathrm{jsf})$ is the last element for calculating $E$, then $\mathrm{jsf}=2 N+1$.

For interior points $k=2,3, \ldots, M$

$$
\begin{aligned}
& \mathrm{s}(1,1)=-1 ; \quad \mathrm{s}(1, \mathrm{ne}+1)=1 ; \quad \mathrm{s}(1, \mathrm{jsf})=\mathrm{y}(1, \mathrm{k})-\mathrm{y}(1, \mathrm{k}-1) \\
& \mathrm{s}(2,4)=0.25^{*} \mathrm{~h}^{*} \mathrm{tmp} 2 * \mathrm{LT} ; \quad \mathrm{s}(2, \mathrm{ne}+4)=\mathrm{s}(2,4) ; \\
& \mathrm{s}(2, \mathrm{ne}+5)=\mathrm{s}(2,5) ; \quad \mathrm{s}(2,5)=0.25^{*} \mathrm{~h}^{*} \mathrm{tmp} 1^{*} \mathrm{LT} \\
& \mathrm{~s}(2, \mathrm{jsf})=\mathrm{y}(2, \mathrm{k})-\mathrm{y}(2, \mathrm{k}-1)+\mathrm{h}^{*}\left(\left(0.25^{*} \mathrm{tmp}^{*}{ }^{*} \text { tmp2} 2 * \text { LT-ni*ni }\right)-\mathrm{g}\right)
\end{aligned}
$$

$$
\mathrm{s}(3,4)=0.5^{*} \mathrm{~h} /\left(\varepsilon \varepsilon_{0}\right) ; \quad \mathrm{s}(3, \mathrm{ne}+4)=\mathrm{s}(3,4)
$$

$$
\mathrm{s}(3,5)=-0.5^{*} \mathrm{~h} /\left(\varepsilon \varepsilon_{0}\right) ; \quad \mathrm{s}(3, \mathrm{ne}+5)=\mathrm{s}(3,5)
$$

$$
\mathrm{s}(3,3)=-1.0 ; \quad \mathrm{s}(3, \mathrm{ne}+3)=1.0
$$

$$
\mathrm{s}(3, \mathrm{jsf})=\mathrm{y}(3, \mathrm{k})-\mathrm{y}(3, \mathrm{k}-1)-0.5^{*} \mathrm{~h}^{*}(\mathrm{tmp} 2-\mathrm{tmp} 1) /\left(\varepsilon \varepsilon_{0}\right)
$$

$$
\mathrm{s}(4,4)=-1 .+\mathrm{h}^{*}(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(4,6)=-.5^{*} \mathrm{~h} / \mathrm{de}
$$

$$
\mathrm{s}(4, \mathrm{ne}+4)=1 .+\mathrm{h}^{*}(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(4, \mathrm{ne}+6)=-.5^{*} \mathrm{~h} / \mathrm{de}
$$

$$
\mathrm{s}(4,3)=\mathrm{h}^{*} \operatorname{tmp} 1 /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(4, \mathrm{ne}+3)=\mathrm{h}^{*} \operatorname{tmp} 1 /\left(4^{*} \mathrm{kt}\right)
$$

$$
\mathrm{s}(4, \mathrm{jsf})=\mathrm{y}(4, \mathrm{k})-\mathrm{y}(4, \mathrm{k}-1)-0.5^{*} \mathrm{~h}^{*}\left((\mathrm{y}(6, \mathrm{k})+\mathrm{y}(6, \mathrm{k}-1)) / \mathrm{de}-\mathrm{tmp} 1^{*}(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(2^{*} \mathrm{kt}\right)\right)
$$

$$
\mathrm{s}(5,5)=-1 .-\mathrm{h} *(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(5,2)=0.5^{*} \mathrm{~h} / \mathrm{dh}
$$

$$
\mathrm{s}(5, \mathrm{ne}+5)=1 .-\mathrm{h}^{*}(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(5, \mathrm{ne}+2)=0.5^{*} \mathrm{~h} / \mathrm{dh}
$$

$$
\mathrm{s}(5,3)=-\mathrm{h}^{*} \operatorname{tmp} 2 /\left(4^{*} \mathrm{kt}\right) ; \quad \mathrm{s}(5, \mathrm{ne}+3)=-\mathrm{h}^{*} \operatorname{tmp} 2 /\left(4^{*} \mathrm{kt}\right)
$$

$$
\mathrm{s}(5, \mathrm{jsf})=\mathrm{y}(5, \mathrm{k})-\mathrm{y}(5, \mathrm{k}-1)+0.5^{*} \mathrm{~h}^{*}\left((\mathrm{y}(2, \mathrm{k})+\mathrm{y}(2, \mathrm{k}-1)) / \mathrm{dh}-\mathrm{tmp} 2^{*}(\mathrm{y}(3, \mathrm{k})+\mathrm{y}(3, \mathrm{k}-1)) /\left(2^{*} \mathrm{kt}\right)\right)
$$

$$
\mathrm{s}(6,6)=-1.0 ; \quad \mathrm{s}(6, \mathrm{ne}+6)=1.0
$$

$$
\begin{aligned}
& \mathrm{s}(6,4)=-0.25^{*} \mathrm{~h}^{*} \text { tmp2*LT; } \mathrm{s}(6, \mathrm{ne}+4)=\mathrm{s}(6,4) \\
& \mathrm{s}(6,5)=-0.25^{*} \mathrm{~h}^{*} \text { tmp1*LT ; } \mathrm{s}(6, \mathrm{ne}+5)=\mathrm{s}(6,5) \\
& \mathrm{s}(6, \mathrm{jsf})=\mathrm{y}(6, \mathrm{k})-\mathrm{y}(6, \mathrm{k}-1)-\mathrm{h} *\left(\left(0.25^{*}\right.\right. \text { tmp1*tmp2*LT-ni*ni)-g) }
\end{aligned}
$$

At the first boundary $(\mathrm{x}=0, \mathrm{k}=1)$

$$
\begin{array}{ll}
\mathrm{s}(4, \mathrm{ne}+3)=1.0 ; & \mathrm{s}(5, \mathrm{ne}+2)=1.0 \\
\mathrm{~s}(6, \mathrm{ne}+4)=1.0 ; & \mathrm{s}(6, \mathrm{ne}+1)=-1.0 \\
\mathrm{~s}(4, \mathrm{jsf})=\mathrm{y}(3,1)-\mathrm{E} 0 ; & \mathrm{s}(5, \mathrm{jsf})=\mathrm{y}(2,1) ;
\end{array}
$$

## At the second boundary $(x=d, k=M)$

$$
\begin{array}{lrl}
\mathrm{s}(1, \mathrm{ne}+3)=1.0 ; & \mathrm{s}(2, \mathrm{ne}+6)=1.0 ; & \mathrm{s}(3, \mathrm{ne}+5)=1.0 \\
\mathrm{~s}(3, \mathrm{ne}+1)=\exp (\mathrm{v} /(\mathrm{kt})))^{*} \mathrm{n}^{*} \mathrm{n} 0 /(\mathrm{y}(1, \mathrm{~m}) * \mathrm{y}(1, \mathrm{~m})) \\
\mathrm{s}(1, \mathrm{jsf})=\mathrm{y}(3, \mathrm{~m})-\mathrm{Ed} ; & \mathrm{s}(2, \text { jsf })=\mathrm{y}(6, \mathrm{~m}) \\
\mathrm{s}(3, \mathrm{jsf})=\mathrm{y}(5, \mathrm{~m})-\exp (\mathrm{v} /(\mathrm{kt}))^{*} \mathrm{n}^{2}{ }^{*} \mathrm{n} 0 / \mathrm{y}(1, \mathrm{~m})
\end{array}
$$

## Initial Guess

In our model, the applied voltage ( V ) is implemented as one boundary condition. The current density is obtained from solution. We start with $V=0 V$, giving a initial guess, solving equations. Then, the solution of $V=0 V$ will be used as the initial guess solution under applied voltage $V=10 \mathrm{mV}$. We increase the voltage with increment of 10 mV , until The desired voltage reached. The first initial guess are shown as below, where D is the thickness of perovskite layer. $m y E 0=V / D$.

The first initial guess
do $\mathrm{k}=1, \mathrm{M}$

$$
\begin{aligned}
& \mathrm{x}(\mathrm{k})=(\mathrm{k}-1)^{*} \mathrm{~h} \\
& \mathrm{y}(1, \mathrm{k})=\mathrm{n} 0^{*} \exp \left(\mathrm{v} /\left(2^{*} \mathrm{kt}\right)\right) \\
& \mathrm{y}(2, \mathrm{k})=0.01^{*} \mathrm{x}(\mathrm{k}) / \mathrm{D}
\end{aligned}
$$

$$
\begin{aligned}
& y(3, k)=\operatorname{myE} 0 \\
& y(4, k)=n 0 * \exp \left(v /\left(2^{*} \mathrm{kt}\right)\right)^{*} \operatorname{EXP}(\mathrm{x}(\mathrm{k}) / \mathrm{D}) \\
& \mathrm{y}(5, \mathrm{k})=\mathrm{n} 0^{*} \exp \left(\mathrm{v} /\left(2^{*} \mathrm{kt}\right)\right)^{*} \operatorname{EXP}(1-\mathrm{x}(\mathrm{k}) / \mathrm{D}) \\
& \mathrm{y}(6, \mathrm{k})=(\mathrm{D}-\mathrm{x}(\mathrm{k}))^{*} 0.01 / \mathrm{D} \\
& \text { end do }
\end{aligned}
$$

## Error calculation and converged criteria

The total error is calculated by

$$
\begin{equation*}
\text { Error }=\frac{1}{6 M} \sum_{k=1}^{M} \sum_{j=1}^{6} \frac{|\Delta y(j, k)|}{\operatorname{scalv}(j)} \tag{14}
\end{equation*}
$$

Where $\operatorname{scalv}(j)$ is the scale of variable $y(j)$. In Numerical recipes, the scalv vector is defined by a constant vector. In this numerical model, charge densities are in the scale of $10^{10}$ to $10^{18}$. If we define its scalv as a constant, the error should in a very wide range. Therefore, we set $\operatorname{scalv}(j)$ as the maximum value of previous $y(j, k)$. The convergence criteria (conv) is $1.0^{-20}$. When error is smaller than conv, the solution was reached.

## Charges densities, electric field and currents in perovskite solar cells

## Mesh test

Here, we are going to test how many discretion points (M) are enough for our model. Models with and without interface recombination are carried out. As shown in Figure 5, for model without interface recombination, 801 points is enough to get a accurate solution. For the sake of safety, we set $M=3001$ for model without interface recombinations. While, for the model with interface, more points are needed. We performed more test with an interface recombination with 2 nm thickness and 1 ns charge carriers lifetime. It is found that there is


Figure 2: I-V charater curve simulated with boundary fields are $F(x=0)=F(x=d)=V / d$. Other parameters are shown in manuscripts Table 1. Charges densities, currents and field at A, B and C points are shown in Figure 3.
no much difference between the solutions solved with $M=20001$ and $M=300001$. As the computation time is about proportional to M points, high density points needs long time. Therefore, we choose $M=20001$ for models with interface recombination for time-saving.

Table 1: Parameters for $M$ test.

| $\alpha$ | Absorption coefficient | $5.7 \times 10^{4} \mathrm{~cm}^{-1} .^{2}$ | T | Temperature | 300 K |
| :--- | :--- | :--- | :--- | :--- | :--- |
| $I P C E$ | IPCE | $100 \%$ | $I_{l}$ | Light intensity | 1.5 AM |
| $N_{c}, N_{v}$ | Density of States | $3.97 \times 10^{18} \mathrm{~cm}^{-3} .^{3}$ | $B g a p$ | Band gap | $1.55 \mathrm{eV}^{4}$ |
| $D_{n}$ | Electron diffusion coefficient | $0.017 \mathrm{~cm}^{2} \mathrm{~s}^{-1} .^{5}$ | $\tau$ | Lifetime | $736 \mathrm{~ns}^{4}$ |
| $D_{p}$ | Hole diffusion coefficient | $0.011 \mathrm{~cm}^{2} \mathrm{~s}^{-1} .{ }^{5}$ | $F_{0}, F_{d}$ | Field at boundary | $\frac{V}{d}$ |
| $d$ | Perovskite thickness | $350 \mathrm{~nm}^{4}$ | $\tau_{\text {intf }}$ | Interface Lifetime | 1 ns |

## Parallelization

With a given V, J is determined by solving Equation 3. Every solution only give one point in J-V curve of a solar cell. On the other hand, the mesh points need to be large in order to achieve accurate solutions. Hence, to draw a J-V curve of a solar cell, it is time-consuming. Here, we implement MPI into our code for parallel calculation. The solution matrix is


Figure 3: Simulated charges densities, electric fields and currents in perovskite solar cells. Left shows parameters at short circuit, point A in figure 2. Right shows parameters near open circiut, point B and C in figure 2.. Boundary fields are $F(x=0)=F(x=d)=V / d$. Other parameters are shown in manuscripts Table 1. The enlarged current distribtion near $\mathrm{TiO}_{2}$ side is shown in Figure 4.


Figure 4: Currents near $\mathrm{TiO}_{2}$ side in perovskite solar cells near open circiut simulated with interfaces. Boundary fields are $F(x=0)=F(x=d)=V / d$. Other parameters are shown in manuscripts Table 1.


Figure 5: I-V curves of a solar cell with different number of mech points and interface recombination thickness. In the interface recombination region, charge carrier's lifetime is set as 1 ns . More parameters are shown in Table 1


Figure 6: I-V curves of a solar cell with different number of mech. The interface recombiantion thickness is 2 nm . More parameters are shown in Table 1
diagonalised by splitting it into M $6 \times 13$ submatrixs and diagonalising the submatrix from $k=1$ to $k=M$. It is not wise to divide this process into several parts and to diagonalise on separated CPUs. Therefore, we scatter all of the V array to every CPU, and then solve them separately. Lastly, all of the solutions are collected by MPI_GATHERV function.

## Lifetime dependence:



Figure 7: Lifetime depends $V_{o c}$ with various lifetimes.


Figure 8: Solar cell's performance with various lifetimes with interface recombination. $F_{0}=F_{d}=V_{0} / d$.


Figure 9: Solar cell's performance with various lifetimes without interface recombination. $F_{0}=F_{d}=V_{0} / d$.

## Mobility dependence:



Figure 10: Solar cell's performance with mobilities. Both of the electron and hole mobilities increase at the same to certain times of 0.65 (electron) and 0.42 (hole) $\mathrm{cm}^{2} / V s$, corresponding to diffusion coefficient of $0.017 \mathrm{~cm}^{2} / \mathrm{s}$ and $0.011 \mathrm{~cm}^{2} / \mathrm{s} . F_{0}=F_{d}=V_{0} / \mathrm{d}$.

## Temperature dependence:



Figure 11: Temperature dependence with diffusion coefficients change. The thickness of simulated solar cell is 350 nm . The band gap is 1.55 eV . The interface recombination width is 5 nm and its lifetime is 5 ns . The lifetime in cell is assumed to be 736 ns . The cells work under 1 sun (1.5AM).

## Thickness depends performance



Figure 12: The thickness dependence PCEs. The optimum thickness is depended on the diffusion length. Modeled with interface. $F_{0}=F_{d}=0$


Figure 13: The thickness dependence PCEs. The optimum thickness is depended on the diffusion length. Modeled without interface. $F_{0}=F_{d}=V / d$


Figure 14: The thickness dependence PCEs. The optimum thickness is depended on the diffusion length. Modeled with interface. $F_{0}=F_{d}=V / d$

## Structure optimization



Figure 15: Models comparison of T and S model with or without interface, with life time of 736 ns or 50 ns. $F_{x=0}=F_{x=d}=\frac{V}{d}$


Figure 16: Models comparison of T and S model with or without interface, with life time of 736 ns or $50 \mathrm{~ns} . F_{x=0}=F_{x=d}=0$

## Recombination coefficient estimation

As we have illustrated before that Equation 14 is the charge carriers lifetime educe from Equation 12 under small charge injection under illumination. ${ }^{6,7}$ While in real case, the condition of small injection is not satisfied. But in experiment only lifetime of the charge carriers are available. Hence, we need to educe the recombination coefficient from lifetime. The lifetime is measure as: ${ }^{2,5}$ They give a short time pulse illumination and then remove it, and measure the charge density. Their process is shown in figure 17. At first, the cell is irradiated by a pulse, during this period time photon generate charge carriers are become more and more until the charge density are saturated. Then remove the pulse, the charge density decrease with time past. After a lifetime period, the charge density become the $\frac{n_{0}}{e}$. Here, we will give the accurate relationship between the lifetime and recombination rate. In experiment, because there is no charge movement and no dopant in perovskite materials, hence, the electron density should be the same with hole density $(n=p)$. Then charge


Figure 17: Measurement of lifetime: In the yellow shadow region, the cell is irradiated by the pulse, in this region photon generate charge carriers are become more and more until the charge density are saturated. Gray shadow covered region means the irradiation have been removed, the charge density decrease with time past.
carriers recombination rate can be expressed as

$$
\frac{d n}{d t}=-R=-r \times n \times p=-r n^{2}
$$

then we have:

$$
n=\frac{1}{r(t-c)}
$$

The measurement process is shown in figure 17. If the charge density dynamics in solar cell have reached a balance before illumination pulse removement. We define the time when pulse remove is zero. At $t=0$, the charge density is $n_{0}$, then we can get $c=\frac{-1}{r n_{0}}$. Hence:

$$
\begin{equation*}
n=\frac{n_{0}}{r n_{0} t+1} \tag{15}
\end{equation*}
$$

## Uniformly distributed charge density

After the pulse removed, if the charge density in the device is uniformly distributed, at time $\tau$, the charge density become $n=\frac{n_{0}}{e}=\frac{n_{0}}{r n_{0} \tau+1}$. Therefore, the lifetime can be expressed as:

$$
\begin{equation*}
\tau=\frac{e-1}{r n_{0}} \tag{16}
\end{equation*}
$$

That's to say the charge carriers lifetime is depend on the initial charge density rather than a certain value. Larger charge density will lead to a short lifetime. If the charge density have reached a balance before measure the lifetime, the charge generation rate should be equal to the recombination rate: $G / d=r \times n_{0}^{2}$. Combining with equation (16), we can get

$$
\begin{equation*}
n_{0}=\frac{G \tau}{L(e-1)} \tag{17}
\end{equation*}
$$

Also we can know the recombination coefficient:

$$
\begin{equation*}
r=\frac{L(e-1)^{2}}{G \tau^{2}}=3.51499 \times 10^{-6} \mathrm{~cm}^{3} / \mathrm{s} \tag{18}
\end{equation*}
$$

Those calculations is based on the assumption that carriers lifetime is 736 ns and charges are generated uniformly.

## Estimation of the initial light intensity at $x=0$

Before the pulse remove, the total generated carriers should be the same with the total recombined carriers. Hence:

$$
\begin{gathered}
\int_{0}^{d} \frac{I_{0}}{L} e^{-x / L} d x=\int_{0}^{d} r n_{0}^{2} e^{-2 x / L} d x \\
I_{0}\left(1-e^{-\frac{d}{L}}\right)=\frac{1}{2} L n_{0}^{2} r\left(1-e^{-\frac{2 d}{L}}\right)
\end{gathered}
$$

We get:

$$
\begin{aligned}
n_{0} & =\sqrt{\frac{2 I_{0}\left(e^{-\frac{d}{L}}-1\right)}{\operatorname{Lr}\left(e^{-\frac{2 d}{L}}-1\right)}} \\
& =\sqrt{\frac{2 I_{0}}{\operatorname{Lr}\left(e^{-\frac{d}{L}}+1\right)}}
\end{aligned}
$$

## Decay exponentially-1

For a more accurate case, the charge density near the light surface is much higher than the charge density inside thin film. This high density will play a very important role in the process of recombination. If the generate rate is exponential decay, the lifetime get more complicated. As the charge recombination is too fast for charge transport. Based on Equation 16, the lifetime at $x$ is

$$
\begin{equation*}
\tau(x)=\frac{e-1}{r n_{x}} \tag{19}
\end{equation*}
$$

Where $n_{x}=n_{0} e^{\frac{-x}{L}}, L$ is the decay depth. $n_{0}$ is the initial light intensity at $x=0$. It will be estimated later. The charge density at $x$ and time $t$ is $n(x, t)=n_{0} e^{\frac{-x}{L}} \times e^{\frac{-t}{\tau(x)}}$. Then the lifetime measured in experiment is the time make below equation true:

$$
\begin{equation*}
\frac{\int_{0}^{d} n_{0} e^{\frac{-x}{L}} \times e^{\frac{-t}{\tau(x)}} d x}{\int_{0}^{d} n_{0} e^{\frac{-x}{L}} d x}=\frac{1}{e} \tag{20}
\end{equation*}
$$

We get,

$$
\begin{equation*}
\frac{(e-1)\left(e^{-\frac{r n_{0} t e}{e-\frac{d}{L}}}-e^{-\frac{r n_{0} t}{e-1}}\right)}{r n_{0} t\left(1-e^{-\frac{d}{L}}\right)}=\frac{1}{e} \tag{21}
\end{equation*}
$$

If we use the data provided by Zhou, ${ }^{4}(\tau=736 \mathrm{~ns}, d=350 \mathrm{~nm}$, band gap $=1.55 \mathrm{eV})$, then $r$ is calculated as $1.23 \times 10^{-9} \mathrm{~cm}^{3} / \mathrm{s}$. The decay curves from the experiment and decay estimated with $r=1.23 \times 10^{-9} \mathrm{~cm}^{3} / \mathrm{s}$ are shown in figure 18 left. As this method is an approximation, if we change $r$ to $1.03 \times 10^{-9} \mathrm{~cm}^{3} / \mathrm{s}$, its fit better, as shown in Figure 18 right.

## Decay directly-2

Rewrite the equation 15 , the carriers density at $x$ and time $t$ is

$$
n(x)=\frac{n_{0}(x)}{r n_{0}(x) t+1}
$$



Figure 18: Coefficient estimation. Decay exponentially-1

If the charge carriers is exponentially occupied at $t=0, n_{0}(x)=\frac{I_{0}}{L} e^{\frac{-x}{L}}$, then the total charge density at time $t$ is

$$
\begin{gathered}
\int_{0}^{d} \frac{n_{0} e^{-\frac{x}{L}}}{n_{0} r t e^{-\frac{x}{L}}+1} d x \\
=\frac{-L \log \left(e^{d / L}+n_{0} r t\right)+d+L \log \left(n_{0} r t+1\right)}{r t}
\end{gathered}
$$

The initial density is $\int_{0}^{d} n_{0} e^{\frac{-x}{L}} d x$

$$
\begin{equation*}
\frac{-L \log \left(e^{d / L}+n_{0} r t\right)+d+L \log \left(n_{0} r t+1\right)}{n_{0} r t\left(L-L e^{-\frac{d}{L}}\right)}=\frac{1}{e} \tag{22}
\end{equation*}
$$



Figure 19: Coefficient estimation. Decay directly-2
If we use the data provided by Zhou, ${ }^{4}(\tau=736 \mathrm{~ns}, d=350 \mathrm{~nm}$, band gap $=1.55 \mathrm{eV})$,
then $r$ is calculated as $1.33 \times 10^{-9} \mathrm{~cm}^{3} / \mathrm{s}$. The decay curves from the experiment and decay estimated with $r=1.33 \times 10^{-9} \mathrm{~cm}^{3} / \mathrm{s}$ are shown in Figure 19. Due to its poor agreement, this method is abandoned.

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