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# **Supporting Information**

### Metal-Free Half-Metallicity in a High Energy Phase C-doped gh-C<sub>3</sub>N<sub>4</sub> System: A High

**Curie Temperature Planar System.** 

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### Text S1. Formation Energy (E<sub>f</sub>) and Binding Energy (E<sub>B</sub>) Calculations

The formation energy  $(E_f)$  is calculated for each C-doped gh-C<sub>3</sub>N<sub>4</sub> using the following equation:

$$E_{f} = (E_{C(N)@gh-C3N4} - E_{gh-C3N4}) - x(\mu_{C} - \mu_{N})]$$
(2)

where  $E_{C(N)@gh-C3N4}$  is the total energy of  $C_N@gh-C_3N_4$ ,  $E_{gh-C3N4}$  is the total energy of gh-C<sub>3</sub>N<sub>4</sub> sheet.  $\mu_C$  and  $\mu_N$  represents the chemical potential of carbon and nitrogen atoms, which are calculated from graphene and N<sub>2</sub>, respectively. We have also calculated the binding energy (E<sub>B</sub>) of carbon in the N-site of gh-C<sub>3</sub>N<sub>4</sub> using the following equation:

$$E_{\rm B} = E_{\rm CN@gh-C3N4} - (E_{\rm gh-C3N4} + xE_{\rm C})$$
(3)

where,  $E_C$  represents the total energy of the isolated C atom.

**Table S1**: Formation energy  $(E_f)$ /dopant, binding energy  $(E_B)$ , magnetic moments (per doped C), Band gap (eV) for  $C_N@gh-C_3N_4$  systems are tabulated. Different doping C-concentrations and their respective values are given.

<b>Doping concentration</b>		$\mathbf{E_{f}}$	$\mathbf{E}_{\mathbf{B}}$	Magnetic	Nature	Band gap
	(%)	(eV)	(eV)	moment (µ <sub>B</sub> )		(eV)
	N1-position	0.52	8.72	0.90	Metallic	
3.12						
	N2-position	1.05	9.06	1.00	Semiconductor	0.92
	N3-position	0.41	8.83	0.80	Metallic	
	N1-position	0.56	8.68	0.90	Metallic	
6.25	N2-position	1.09	9.04	1.00	Semiconductor	0.86
	N3-position	0.45	8.81	0.80	Metallic	
	N1-position	0.56	8.53	0.90	Metallic	
9.37	N2-position	1.02	9.17	1.00	Semiconductor	0.59
	N3-position	0.42	8.72	0.80	Metallic	
	N1-position	0.55	8.44	0.90	Semiconductor	Up-spin: 1.98
						Down-spin: 0.33
12.50	N2-position	1.12	9.12	1.00	Half-metallic	Up-spin: Metallic
						Down-spin: 1.45
	N3-position	0.43	8.67	0.80	Semiconductor	Up-spin: 2.10
						Down-spin: 0.13



**Figure S1**: (a) Optimized structure, TDOS/PDOS and Band Structure of  $C_{N1}@gh-C_3N_4$ . (b) Optimized structure, TDOS/PDOS and Band Structure of  $C_{N3}@gh-C_3N_4$ . A red dashed box shows unitcell. The Fermi level is indicated by a black dashed line.



Figure S2: Total and partial DOS of C<sub>N2</sub>@gh-C<sub>3</sub>N<sub>4</sub> using HSE06 functional.



Figure S3: Partial DOS of (a)  $C_{N1}@gh-C_3N_4$ , (b)  $C_{N2}@gh-C_3N_4$  and (c)  $C_{N3}@gh-C_3N_4$ .



Figure S4: Schematic representation of  $sp^2$  hybridization in  $C_N@gh-C_3N_4$ .

**Table S2**: Bader charges of  $C_N@gh-C_3N_4$  systems.



Figure S5: The structure of (a) pure  $gh-C_3N_4$ , (b)  $C_{N1}@gh-C_3N_4$ , (c)  $C_{N2}@gh-C_3N_4$ , and (d)

$C_{N3}@gh-C_3N_{4.}$	The black	dashed	circle	denotes	the doped	C-atom.
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System	Net Effective Charges			
	С	N		
gh-C <sub>3</sub> N <sub>4</sub>	C1=+1.75	N1= -1.03		
	C2=C3=+1.42	N2= -1.07		
	C4 = +1.64	N3= -1.17		
	C5=C6=C7=+1.37			
C <sub>N1</sub> @gh-C <sub>3</sub> N <sub>4</sub>	C4=C5=C6=+1.06	N2= -1.15		
	$C_{N1} = +0.25$	N3= -1.09		
C <sub>N2</sub> @gh-C <sub>3</sub> N <sub>4</sub>	C2=+0.84	N1=-1.08		
	C7=+0.83	N3= -1.23		
	$C_{N2} = +0.26$			
C <sub>N3</sub> @gh-C <sub>3</sub> N <sub>4</sub>	C1=C2=C3=+1.04	N1=-1.11		
-	$C_{N3} = +0.14$	N2= -1.13		



**Figure S6**: Electrostatic potentials (ESP) plots (Isosurface value: 0.09 e.Å<sup>-3</sup>) of (a) pure gh- $C_3N_4$ , (b)  $C_{N1}@gh-C_3N_4$ , (c)  $C_{N2}@gh-C_3N_4$ , and (d)  $C_{N3}@gh-C_3N_4$ . The blue and red colours denote less and more electron dense area in the electrostatic potential surface.



**Figure S7**: Optimized structures and total and partial density of states of 3.12% (a)  $C_{N1}@gh-C_3N_4$ , (b)  $C_{N2}@gh-C_3N_4$ , and (c)  $C_{N3}@gh-C_3N_4$  systems. A red dashed box shows unitcell.



**Figure S8**: Optimized structures and total and partial density of states of 6.25% (a)  $C_{N1}@gh-C_3N_4$ , (b)  $C_{N2}@gh-C_3N_4$ , and (c)  $C_{N3}@gh-C_3N_4$  systems. A red dashed box shows unitcell.



Figure S9: Optimized structures and total and partial density of states of 9.37% (a)  $C_{N1}@gh-C_3N_4$ , (b)  $C_{N2}@gh-C_3N_4$ , and (c)  $C_{N3}@gh-C_3N_4$  systems. A red dashed box shows unitcell.



**Figure S10:** Total energy fluctuation during AIMD simulations of (a)  $C_{N1}@gh-C_3N_4$ , and (b)  $C_{N3}@gh-C_3N_4$  systems at 500 and 1000 K. The structures represent the snapshot at 10 ps for each simulation.

### Text S2: Calculation of mechanical properties

The  $C_{N2}@gh-C_3N_4$  monolayer sheets can be distorted either by tensile strain (by gradually increasing the lattice parameters) or compressive strain (by gradually reducing the lattice parameters). The percentage (%) of applied strain can be calculated as follows.<sup>1</sup>

% Strain = 
$$(a-a_1)/a \times 100$$
 (4)

Here 'a' and 'a<sub>1</sub>' are the lattice constants of the monolayer sheet before and after the strain. Tensile strains are applied along the in-plane uniaxial and biaxial directions to calculate the mechanical stability of  $C_{N2}@gh-C_3N_4$  system. The effects of uniaxial and biaxial strains are examined on a supercell  $(2\times2\times1)$  of 56 atoms. Atomic positions are relaxed at each strain until the forces on each atom are less than  $10^{-2}$  eV/Å. Elastic limit is calculated from the stress-strain curve under the tensile stretch given in the manuscript in Figure 4c.<sup>2</sup>

Further, the mechanical properties of the  $C_{N2}@gh-C_3N_4$  sheets can be calculated from the strain vs. strain energy plot [Figure 4b, Manuscript]. The elastic energy (U/per unit cell) near the equilibrium position can be calculated using the following formula:

$$U = \frac{1}{2}C_{11}\varepsilon_{xx}^2 + \frac{1}{2}C_{22}\varepsilon_{yy}^2 + C_{12}\varepsilon_{xx}\varepsilon_{yy} + 2C_{44}\varepsilon_{xy}^2$$
(5)

where,  $C_{11}$ ,  $C_{22}$ ,  $C_{12}$  and  $C_{44}$  are the linear elastic constants, whereas  $\varepsilon_{xx}$ ,  $\varepsilon_{yy}$ ,  $\varepsilon_{xy}$  are the inplane stress along the *x*, *y* and *xy* directions (according to Voigt notation),<sup>4</sup> respectively. The value of the elastic constants can be calculated from the polynomial fitting of strain *vs*. energy plot.<sup>4-6</sup> The main criteria for mechanical stability are  $C_{11} > C_{12}$  and  $C_{44} > 0$ . The value of  $C_{11}$  can be obtained under uniaxial deformation, whereas  $C_{12}$  can be calculated by polynomial fitting under biaxial deformation. For all three  $C_{N2}@gh-C_3N_4$  systems, we find that  $C_{11} > C_{12}$  and  $C_{44} > 0$ . Thereby, the calculated elastic constants of  $C_{N2}@gh-C_3N_4$  sheets satisfy all the criteria to be mechanically stable. Young's modulus (Y) and Poisson's ratio (PR) are calculated using the following formulas.<sup>3</sup>

$$\mathbf{Y} = (\mathbf{C}_{11}^2 - \mathbf{C}_{12}^2) / \mathbf{C}_{11}$$
(6)

$$PR = C_{12}/C_{11}$$
(7)

**Table S3**: Exchange energy ( $E_{ex}$ ) and Curie temperature ( $T_C$ ) value of 12.50%  $C_N@gh-C_3N_4$  system.

	Magnetic	Exchange energy	Energy Difference	Curie	MAE in (µeV)/C
Compound	Moment/	(meV)/C	(meV)/C	Temperature	(Magnetic
	С	$[\mathbf{E}_{\mathrm{ex}} = \mathbf{E}_{\mathrm{FM}} - \mathbf{E}_{\mathrm{AFM}}]$	$(\mathbf{E}_{diff} = \mathbf{E}_{FM} - \mathbf{E}_{NSP})$	(T <sub>C</sub> ) in (K)	Anisotropy
	(µ <sub>B</sub> )				Energy)
$C_{N1}@gh-C_3N_4$	0.90	-111.41	-47.89	294	9.83
$C_{N2}@gh-C_3N_4$	1.00	-151.54	-30.26	402	12.20
$C_{N3}@gh-C_3N_4$	0.80	-75.53	-22.31	204	7.36

Text S3. Calculation of Magnetic Anisotropy Energy (MAE)

The magnetic anisotropy energy (MAE) is calculated by applying the torque approach.<sup>7-8</sup> Non-collinear self-consistent calculations (including spin orbit coupling) are performed in the z, y and x axis magnetization directions, respectively. MAE originates from the perpendicular and in plane contribution of spin orbit coupling (SOC), which can be expressed in terms of angular momentum operators  $L_x$ ,  $L_y$  or  $L_z$ . So the contribution of different spins (up ' $\uparrow$ †' and down ' $\downarrow\downarrow$ ') can be expressed by the second order perturbation equation.<sup>6</sup>

$$MAE = \xi^{2} \sum_{o,u} \frac{| < o | L_{Z} | u > |^{2} - | < o | L_{X} | u > |^{2}}{E_{u} - E_{o}}$$

Here, o and u represent the occupied and unoccupied electronic states, respectively. The  $E_o$  and  $E_u$  in the denominator are their respective band energies.  $L_Z$  and  $L_X$  are the angular momentum operators along Z and X axis, and  $\xi$  denotes the strength of the SOC. So, a potential with good MAE for practical application should hold a high value of  $\xi$ . Then, the MAE is calculated using the following equation:

$$MAE = E_{S0} - E_{S1} \tag{8}$$

Where  $E_{S0}$  is the energy of the materials without employing any magnetic axis and  $E_{S1}$  is the energy in presence of an easy axis. Total energies are converged to a precision of  $10^{-6}$  eV in MAE calculations.

### Text S3.1 Mean Field Theory (MFT):

We have taken the MFT approach to calculate the Curie tempareture for the two dimentional  $C_N@gh-C_3N_4$  systems. This method has been previously used by Li et al.<sup>9</sup> for the Curie tempareture calculation for Mn-phthalocyanine (MnPc) system. The main idea behind MFT method is to replace all interactions to any one body with an average or effective interaction.<sup>10</sup> It reduces any multi-body problem into an effective one-body problem. The detailed partition function can be written as follows,

$$Z = \sum_{m = -M, -M+2, \dots, M-2, M} e^{\gamma J' m < M > /k_B T}$$
(9)

Here, 'J' is the exchange parameter, ' $\gamma$ ' is the coordination number, 'm' is the ensembleaverage magnetic moment, and 'M' is the calculated magnetic moment of the system.

Thus, the average spin of each magnet becomes,

$$= \frac{1}{Z} \sum_{m=-M,-M+2,...,M-2,M} m \times e^{\gamma J' m < M > /k_B T}$$
 (10)

Now, if we assume that,  $P = \frac{\gamma J'}{k_B T}$ , then the equation 5 becomes,

The above equation can be easily deducible when the parameter 'P' varies along with the static solution <m>. At the critical point,

$$\mathbf{P} = \mathbf{P}_{c} = \frac{\gamma J'}{k_{B} T_{c}} \tag{11}$$

At this critical point, the phase transition of the system between ferromagnetic to paramagnetic occurs. This critical point is known as Curie temperature.

#### 3.2 Monte Carlo Simulations:

Monte Carlo simulations involve generating a subset of configurations or samples, chosen using a random algorithm from a configuration space, according to a probability distribution or weight function. Observables are then computed as averages over the samples.<sup>11</sup>

One sample or configuration of the magnet is a particular assignment of spin values, say

$$s_1 = +1; s_2 = -1; s_3 = +1; \dots; s_{Ns} = +1$$
 (12)

in which each spin is set "up" or "down". According to statistical mechanics, the average value of an observable is got by weighting each configuration with the Boltzmann factor. For example, the average magnetization at some fixed temperature T is given by,

$$<\mathbf{M}> = \frac{\sum_{config} M e^{-E/k_B T}}{\sum_{config} e^{-E/k_B T}}$$
(13)

At the Curie temperature  $(T_c)$  we expect a marked fluctuation in the magnetic moment (M).

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