## 1 Two disc ion detection problem

We consider the problem of an inlaid disc of radius $a$ subjected to a constant flux of $\mathrm{H}+$ ions, with no flux boundary conditions on the rest of the plane. The $\mathrm{H}+$ ions are subject to a reversible reaction with a base A- in the bulk solution, with product B :

$$
\begin{equation*}
H+A \underset{k_{b}}{\stackrel{k_{f}}{\rightleftharpoons}} B \tag{1}
\end{equation*}
$$

so that the forward and back rate constants are given by $k_{f}\left(\mathrm{~mol}^{-1} \mathrm{~m}^{3} \mathrm{~s}^{-1}\right)$ and $k_{b}\left(\mathrm{~s}^{-1}\right)$ respectively. We would like to know how the concentration varies across the plane. In particular we would like to know what the concentration is on an inlaid detector disc of radius $b$, whose centre is a distance $L$ away from the centre of the first disc.

Ingoring any electric effects and seeking only steady solutions, the governing equations for the concentration of the three species $H, A$ and $B$, are

$$
\begin{align*}
D_{H} \nabla^{2} H & =k_{f} H A-k_{b} B  \tag{2}\\
D_{A} \nabla^{2} A & =k_{f} H A-k_{b} B  \tag{3}\\
D_{B} \nabla^{2} B & =-k_{f} H A+k_{b} B \tag{4}
\end{align*}
$$

The boundary conditions for $H$ are given by

$$
\begin{align*}
D_{H} \frac{\partial H}{\partial z} & =-Q, \quad \text { for } r<a, z=0  \tag{5}\\
\frac{\partial H}{\partial z} & =0, \quad \text { for } r>a, z=0  \tag{6}\\
H(r, z) & \rightarrow 0, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{7}
\end{align*}
$$

Here $Q$ is the constant flux of ions from the disc, and has the dimensions mol $\mathrm{m}^{-2} \mathrm{~s}^{-1}$. We shall also assume that the diffusion coefficient is constant, and we assume that the bulk concentration of $H$ is zero.

The boundary conditions for $A$ are:

$$
\begin{align*}
\frac{\partial A}{\partial z} & =0, \quad \text { on } z=0  \tag{8}\\
A(r, z) & \rightarrow A_{\infty}, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{9}
\end{align*}
$$

where $A_{\infty}$ is the bulk concentration of the base.

The boundary conditions for $B$ are:

$$
\begin{align*}
\frac{\partial B}{\partial z} & =0, \quad \text { on } z=0  \tag{10}\\
B(r, z) & \rightarrow 0, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{11}
\end{align*}
$$

The first thing we note is that by adding (3) and (4), and using the boundary conditions for $A$ and $B$, it follows that

$$
\begin{equation*}
\nabla^{2}\left(D_{A} A+D_{B} B\right)=0 \tag{12}
\end{equation*}
$$

subject to the boundary conditions

$$
\begin{align*}
\frac{\partial\left(D_{A} A+D_{B} B\right)}{\partial z} & =0, \quad \text { on } z=0,  \tag{13}\\
D_{A} A+D_{B} B & \rightarrow D_{A} A_{\infty}, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{14}
\end{align*}
$$

This means that the quantity $D_{A} A+D_{B} B$ is conserved, and

$$
\begin{equation*}
D_{A} A+D_{B} B=D_{A} A_{\infty} \tag{15}
\end{equation*}
$$

Solving for $B$ and substituting in, we find that the governing equations reduce to two equations for $H$ and $A$ :

$$
\begin{align*}
D_{H} \nabla^{2} H & =k_{f} H A-\frac{k_{b} D_{A}}{D_{B}}\left(A_{\infty}-A\right),  \tag{16}\\
D_{A} \nabla^{2} A & =k_{f} H A-\frac{k_{b} D_{A}}{D_{B}}\left(A_{\infty}-A\right) . \tag{17}
\end{align*}
$$

To non-dimensionalise, we choose the following scalings:

$$
\begin{equation*}
r=a \hat{r}, \quad z=a \hat{z}, \quad H=\frac{Q a}{D_{H}} \hat{H}, \quad A=A_{\infty} \hat{A} . \tag{18}
\end{equation*}
$$

On dropping the hats, the equations become

$$
\begin{align*}
\nabla^{2} H & =k_{1} H A-k_{2}(1-A),  \tag{19}\\
k_{3} \nabla^{2} A & =k_{1} H A-k_{2}(1-A) \tag{20}
\end{align*}
$$

where the non-dimensional parameters $k_{1}, k_{2}$ and $k_{3}$ are given by

$$
\begin{equation*}
k_{1}=\frac{k_{f} a^{2} A_{\infty}}{D_{H}}, \quad k_{2}=\frac{k_{b} a A_{\infty} D_{A}}{Q D_{B}}, \quad k_{3}=\frac{A_{\infty} D_{A}}{Q a} . \tag{21}
\end{equation*}
$$

The boundary conditions for $H$ are

$$
\begin{align*}
\frac{\partial H}{\partial z} & =-1, \quad \text { for } r<1, z=0  \tag{22}\\
\frac{\partial H}{\partial z} & =0, \quad \text { for } r>1, z=0  \tag{23}\\
H(r, z) & \rightarrow 0, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{24}
\end{align*}
$$

and boundary conditions for $A$

$$
\begin{align*}
\frac{\partial A}{\partial z} & =0, \quad \text { on } z=0  \tag{25}\\
A(r, z) & \rightarrow 1, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{26}
\end{align*}
$$

Now we note that if we subtract (20) from (19) we find that

$$
\begin{equation*}
\nabla^{2}\left(H-k_{3} A\right)=0, \tag{27}
\end{equation*}
$$

with boundary conditions

$$
\begin{align*}
\frac{\partial\left(H-k_{3} A\right)}{\partial z} & =-1, \quad \text { for } r<1, z=0  \tag{28}\\
\frac{\partial\left(H-k_{3} A\right)}{\partial z} & =0, \quad \text { for } r>1, z=0  \tag{29}\\
\left(H-k_{3} A\right) & \rightarrow-k_{3}, \quad \text { as }|\mathbf{r}| \rightarrow \infty \tag{30}
\end{align*}
$$

Using the Hankel transform, it is easy to show that the solution to this problem is given by

$$
\begin{equation*}
H(r, z)-k_{3} A(r, z)=-k_{3}+\int_{0}^{\infty} J_{0}(\alpha r) J_{1}(\alpha) \exp (-\alpha z) \frac{d \alpha}{\alpha} \tag{31}
\end{equation*}
$$

where $J_{0}$ and $J_{1}$ are Bessel functions of order zero and one. The concentration of $H$ on the plane $z=0$ is therefore given by

$$
\begin{equation*}
H(r, 0)=\int_{0}^{\infty} J_{0}(\alpha r) J_{1}(\alpha) \frac{d \alpha}{\alpha}-k_{3}(1-A(r, 0)) \tag{32}
\end{equation*}
$$

This means that the concentration of $H$ is equal to the concentration for a disk generator with no reaction less the amount that has reacted with $A$,
which is proportional to $(1-A)$. It is very important to note that the reaction with $A$ only makes a noticeable difference to the concentration of $H$ detected if $k_{3}$ is at least $O(1)$. This is vital in determining sensor design.

From (31), we may write

$$
\begin{equation*}
H(r, z)=k_{3}(A(r, z)-1)+H_{1}(r, z) \tag{33}
\end{equation*}
$$

where $H_{1}$ is the solution for the disc generator with no bulk reaction, which we emphasize is known. Substituting into (20), we find a governing equation for $A$

$$
\begin{align*}
\nabla^{2} A & =k_{1}(A-1) A+\frac{k_{1}}{k_{3}} A H_{1}-\frac{k_{2}}{k_{3}}(1-A)  \tag{34}\\
& =k_{1} A^{2}+A\left(\frac{k_{1}}{k_{3}} H_{1}+\frac{k_{2}}{k_{3}}-k_{1}\right)-\frac{k_{2}}{k_{3}} \tag{35}
\end{align*}
$$

with boundary conditions (25) and (26). Hence we have reduced three governing equations down to one governing equation for $A$ with simple boundary conditions. It is still a complicated equation, and is non-linear in $A$, but we may be able to do some asymptotics depending on the sizes of the parameters $k_{1}, k_{2}$ and $k_{3}$. We shall assume that $Q$ has been chosen such that $k_{3}=O(1)$.

We note that in general $k_{f}$ and $k_{b}$ have the following magnitudes

$$
\begin{align*}
k_{f} & \approx 10^{6}-10^{7} \mathrm{~mol}^{-1} \mathrm{~m}^{3} \mathrm{~s}^{-1}  \tag{36}\\
k_{b} & \approx 10^{3}-10^{4} \mathrm{~s}^{-1} \tag{37}
\end{align*}
$$

This implies that $k_{1}$ will be large, while depending on the value of $Q, k_{2}$ will be around $O(1)$. Dividing through by $k_{1}$, the governing equation becomes:

$$
\begin{equation*}
\frac{1}{k_{1}} \nabla^{2} A=A^{2}+A\left(\frac{1}{k_{3}} H_{1}+\frac{k_{2}}{k_{1} k_{3}}-1\right)-\frac{k_{2}}{k_{1} k_{3}} . \tag{38}
\end{equation*}
$$

Provided that we are not near the disc then the lefthand side may be neglected and the solution to the following quadratic satisifes the boundary conditions (25) and (26):

$$
\begin{equation*}
A^{2}+A\left(\frac{1}{k_{3}} H_{1}+\frac{k_{2}}{k_{1} k_{3}}-1\right)-\frac{k_{2}}{k_{1} k_{3}}=0 \tag{39}
\end{equation*}
$$

so that

$$
\begin{equation*}
A=\frac{1}{2}\left(-\left(\frac{1}{k_{3}} H_{1}+\frac{k_{2}}{k_{1} k_{3}}-1\right)+\sqrt{\left(\frac{1}{k_{3}} H_{1}+\frac{k_{2}}{k_{1} k_{3}}-1\right)^{2}+4 \frac{k_{2}}{k_{1} k_{3}}}\right) \tag{40}
\end{equation*}
$$

where we have taken the positive square root to ensure that $A>0$. Inserting this into (33) we obtain

$$
\begin{equation*}
H(r, z)=\frac{1}{2}\left(H_{1}(r, z)-\frac{k_{2}}{k_{1}}-k_{3}+\sqrt{\left(H_{1}(r, z)+\frac{k_{2}}{k_{1}}-k_{3}\right)^{2}+4 \frac{k_{2} k_{3}}{k_{1}}}\right) . \tag{41}
\end{equation*}
$$

In the limit that $k_{2} / k_{1} \ll 1$, we have to be a bit more careful. Letting $k_{2} / k_{1}=\epsilon$, and expanding the original quadratic in powers of $\epsilon$, so that

$$
\begin{equation*}
A=A_{0}+\epsilon A_{1}+\epsilon^{2} A_{2}+\ldots \tag{42}
\end{equation*}
$$

Then the solution is given by

$$
\begin{align*}
A_{0} & =1-\frac{H_{1}}{k_{3}}  \tag{43}\\
A_{1} & =\frac{H_{1}}{k_{3}\left(k_{3}-H_{1}\right)} . \tag{44}
\end{align*}
$$

## 2 Concentration on disc far away

Suppose that we now would like to measure the concentration on a disc whose centre is a non-dimensional distance $\lambda$ away from the centre of the generator disc, and let us assume that $\lambda \gg 1$. Then it is convenient to write the solution for $H_{1}(r, z)$ in the following form:

$$
\begin{equation*}
H_{1}(r, z)=\frac{2}{\pi} \int_{0}^{1} \mathrm{~K}\left(\frac{2 \sqrt{r s}}{(r+s)^{2}+z^{2}}\right) \frac{s d s}{\sqrt{(r+s)^{2}+z^{2}}} \tag{45}
\end{equation*}
$$

where $\mathrm{K}(\cdot)$ denotes a complete elliptic integral of the first kind. Then the far field behaviour as $r \rightarrow \infty$ on $z=0$ is easily shown to be

$$
\begin{equation*}
H_{1}(r, z) \sim \frac{1}{2 r}+O\left(\frac{1}{r^{3}}\right) \tag{46}
\end{equation*}
$$

so that the disc is a point source as expected. Subtituting this into the solution (49), we obtain:

$$
\begin{equation*}
H(r, z) \sim \frac{1}{2}\left(\frac{1}{2 r}-\frac{k_{2}}{k_{1}}-k_{3}+\sqrt{\left(\frac{1}{2 r}+\frac{k_{2}}{k_{1}}-k_{3}\right)^{2}+4 \frac{k_{2} k_{3}}{k_{1}}}\right) . \tag{47}
\end{equation*}
$$

Writing $r$ in terms of a cylindrical coordinate system $(s, \theta)$ centered at the centre of the detection disc, so that

$$
\begin{equation*}
r=\sqrt{\lambda^{2}+2 \lambda s \cos \theta+s^{2}} \tag{48}
\end{equation*}
$$

and expanding in powers of $\lambda$, we obtain:

$$
\begin{equation*}
H(s, \theta) \sim \frac{k_{2}}{2\left(k_{2}+k_{1} k_{3}\right) \lambda}+\frac{k_{2}\left(k_{1}^{2} k_{3}-2\left(k_{2}+k_{1} k_{3}\right)^{2} s \cos \theta\right)}{4\left(k_{2}+k_{1} k_{3}\right)^{3} \lambda^{2}}+O\left(\frac{1}{\lambda^{3}}\right) . \tag{49}
\end{equation*}
$$

Hence the average concentration across the detection disc is given by (assuming that the non-dimensional radius is $b$ ):

$$
\begin{align*}
H_{\mathrm{Av}} & =\frac{1}{\pi b^{2}} \int_{0}^{b} \int_{0}^{2 \pi} H(s, \theta) s d s d \theta  \tag{50}\\
& =\frac{k_{2}}{2\left(k_{2}+k_{1} k_{3}\right) \lambda}+O\left(\frac{1}{\lambda^{2}}\right) \tag{51}
\end{align*}
$$

In dimensional terms, we have to leading order

$$
\begin{equation*}
H_{\mathrm{Av}, \operatorname{dim}}=\frac{Q a}{2\left(D_{H}+\frac{k_{f}}{k_{b}} A_{\infty} D_{B}\right) \lambda} \tag{52}
\end{equation*}
$$

