

Supplementary Material for “Structure–property relationships of cell clusters in biotissues: 2D analysis”

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S.1. Details of the equilibrium shape equations without volume constraint

The shape equations for the S_1 part in $0 \leq s \leq s_0$ can be written as

$$\kappa_1 \ddot{\phi}_1 - \Delta p_1 x_1 \cos \phi_1 - \lambda_1 \sin \phi_1 = 0, \quad (S1)$$

$$\Delta p_1 x_1 \cos \phi_1 - \lambda_1 = 0. \quad (S2)$$

For the S_3 part in $s_0 \leq s \leq s_0 + \frac{B}{2}$, there are

$$\kappa_3 \ddot{\phi}_3 - \Delta p_3 x_3 \cos \phi_3 - \lambda_3 \sin \phi_3 = 0, \quad (S3)$$

$$\Delta p_3 x_3 \cos \phi_3 - \lambda_3 = 0. \quad (S4)$$

At the initial contact point $s = s_0$, the boundary conditions in Eqs. 4, 5 and 6 are changed to

$$\kappa_1 \dot{\phi}_1^2 + \kappa_2 \dot{\phi}_2^2 - \kappa_3 \dot{\phi}_{12}^2 = 2\omega, \quad (S5)$$

$$\kappa_1 \ddot{\phi}_1 + \kappa_2 \ddot{\phi}_2 - \kappa_3 \ddot{\phi}_3 = 0, \quad (S6)$$

$$\kappa_1 \dot{\phi}_1 + \kappa_2 \dot{\phi}_2 - \kappa_3 \dot{\phi}_3 = 0. \quad (S7)$$

Considering that all cells are equal, we have $\kappa_1 = \kappa_2 = \kappa_3/2 = \kappa$. Note that the S_1 and S_2 parts should be equal in a periodic system, and that the rotation directions of them are opposite in the adhesion region, at the point $s = s_0$, there are

$$\dot{\phi}_1 = -\dot{\phi}_2, \quad \ddot{\phi}_1 = -\ddot{\phi}_2, \quad \phi_3 = \ddot{\phi}_3 = 0. \quad (S8)$$

The above conditions make sure that Eqs. 20 and 21 can be satisfied, and Eq. 19 is reduced to

$$\omega = \kappa \dot{\phi}_1^2, \quad (s = s_0). \quad (S9)$$

Due to each adhesion part is a straight line, ϕ_3 should be independent to s and we choose $\phi_3 \equiv \phi_0 = \pi/n$. One can find that $n = 2, 4$ and 6 correspond to the shapes in Fig. 2(d), (e) and (f), respectively. In order to obtain dimensionless results, we choose $\kappa = 1$ and fix the girth of each cell $L = \oint ds = 2\pi$.

First, we study the structures without volume constraint for each cell, which means the pressure difference $\Delta p_i = 0$. For convenient, in the following text we choose $\lambda_1 = \lambda$, $\phi_1 = \phi$, and $x_1 = x$. The shape equations for the S_1 part can be reduced to

$$\ddot{\phi} = \lambda \sin \phi, \quad (0 \leq s \leq s_0). \quad (S10)$$

The first integral is

$$\dot{\phi}^2 = 2\lambda(C - \cos \phi), \quad (S11)$$

where C is an integral constant. Consequently, we have

$$ds = \frac{d\phi}{\sqrt{2\lambda(C - \cos \phi)}}. \quad (S12)$$

Choosing the initial conditions $x(0) = 0$, $y(0) = 0$, and $\phi(0) = 0$ and using the Eq. 7, the coordinates at the point $s = s_0$ are

$$\begin{aligned} x_0 &= \int_0^{s_0} \cos \phi ds = \int_0^{\phi_0} \frac{\cos \phi d\phi}{\sqrt{2\lambda(C - \cos \phi)}} \\ &= \sqrt{\frac{2}{\lambda(C-1)}} \times \left[C \times FN \left[\frac{\phi_0}{2}, \frac{2}{1-C} \right] - (C-1) \times SN \left[\frac{\phi_0}{2}, \frac{2}{1-C} \right] \right], \end{aligned} \quad (S13)$$

$$y_0 = \int_0^{s_0} \sin \phi ds = \int_0^{\phi_0} \frac{\sin \phi d\phi}{\sqrt{2\lambda(C - \cos \phi)}} = \sqrt{\frac{2}{\lambda}} (\sqrt{C - \cos \phi_0} - \sqrt{C - 1}), \quad (S14)$$

where $FN[x, y]$ and $SN[x, y]$ are the first and second incomplete elliptical integral, respectively. The length

constraint $L = \oint ds = 2\pi$ gives the following equation

$$s_0 + \frac{B}{2} = \int_0^{\phi_0} \frac{d\phi}{\sqrt{2\lambda(C - \cos \phi)}} + \frac{B}{2} = \phi_0. \quad (S15)$$

It yields

$$\sqrt{\frac{2}{\lambda(C - 1)}} \times FN\left[\frac{\phi_0}{2}, \frac{2}{1 - C}\right] + \frac{B}{2} = \phi_0. \quad (S16)$$

Making use of Eq. S11, condition S9 is changed to

$$\lambda = \frac{\omega}{2(C - \cos \phi_0)}. \quad (S17)$$

Substituting the above equation into Eq. S16, we get

$$B = 2\phi_0 - 4 \sqrt{\frac{C - \cos \phi_0}{\omega(C - 1)}} \times FN\left[\frac{\phi_0}{2}, \frac{2}{1 - C}\right]. \quad (S18)$$

The diameters of the inscribed circle and circumscribed circle of each cell in Fig. 2 are

$$R = 2x_0 \csc \phi_0 + B \cot \phi_0, \quad (S19)$$

$$H = 2x_0 \cot \phi_0 + B \csc \phi_0 + 2y_0, \quad (S20)$$

The dimensionless total energy for each cell is

$$\begin{aligned} E &= \frac{2\pi}{\phi_0} \left(\int_0^{s_0} \frac{1}{2} \dot{\phi}^2 ds - \frac{1}{4} \omega B \right) = \frac{2\pi}{\phi_0} \int_0^{\phi_0} \frac{\lambda(C - \cos \phi)}{\sqrt{2\lambda(C - \cos \phi)}} d\phi - \frac{\pi}{2\phi_0} \omega B \\ &= \frac{2\pi}{\phi_0} \sqrt{2\lambda(C - 1)} \times SN\left[\frac{\phi_0}{2}, \frac{2}{1 - C}\right] - \frac{\pi}{2\phi_0} \omega B. \end{aligned} \quad (S21)$$

Substituting Eqs. S17 and S18 into the above equation, we obtain

$$E = \frac{2\pi}{\phi_0} \sqrt{\frac{\omega(C - 1)}{C - \cos \phi_0}} \times SN\left[\frac{\phi_0}{2}, \frac{2}{1 - C}\right] - \pi\omega + \frac{2\pi}{\phi_0} \sqrt{\frac{\omega(C - \cos \phi_0)}{C - 1}} \times FN\left[\frac{\phi_0}{2}, \frac{2}{1 - C}\right]. \quad (S22)$$

In the above equation, if ω and ϕ_0 are known, there is only an unknown constant C . Defining $\chi = 1/C$, the equilibrium shapes satisfy

$$\frac{dE}{dR} = \frac{dE/d\chi}{dR/d\chi} = 0. \quad (S23)$$

We find it needs $\chi \rightarrow 0$ ($C \rightarrow \pm \infty$). Then substituting Eq. S17 into Eq. S11, we have

$$\dot{\phi}^2 = \frac{\omega(C - \cos \phi)}{C - \cos \phi_0} = \omega, \quad (S24)$$

This result indicates that the optimal shapes of the free parts in Fig. 2 are circular arcs with the same radius $r_0 = \sqrt{1/\omega}$ and the total energy for each cell $E = 2\pi\sqrt{\omega} - \pi\omega$. Then the equilibrium distance between two cell is $R_0 = 2r_0 + B \cot \phi_0 = 2\sqrt{1/\omega} + 2(1 - \sqrt{1/\omega}) \phi_0 \cot \phi_0$. (S25)

It is the result in Eq. 16.

5.2. Surface Evolver code for bead-like structure

Here we show a bead-like structure composed by three cells adhere together. This model needs to run on

the Surface Evolver 2.70s.

// Surface Evolver code for bead-like structure composed by three cells.

SPACE_DIMENSION 2

STRING

PARAMETER ad = -4 // ad is the adhesion potential

PARAMETER inputrv = 0.9 // inputrv is the reduced volume

VIEW_MATRIX

1.0000000000000000 0.0000000000000000 -0.9520000000000001

0.0000000000000000 1.0000000000000000 -0.7000000000000000

0.0000000000000000 0.0000000000000000 1.0000000000000000

define edge attribute sqcurve_string_mark integer

QUANTITY sqc_c1 ENERGY method sqcurve_string_marked global modulus 0.5 parameter_2 1

QUANTITY sqc_c2 ENERGY method sqcurve_string_marked global modulus 0.5 parameter_2 2

QUANTITY sqc_c3 ENERGY method sqcurve_string_marked global modulus 0.5 parameter_2 4

QUANTITY c1_length FIXED = 2*Pi method edge_length

QUANTITY c2_length FIXED = 2*Pi method edge_length

QUANTITY c3_length FIXED = 2*Pi method edge_length

vertices /* coordinates */

1 0 0

2 1 0

3 0 1

4 1 1

5 0 2

6 1 2

7 0 3

8 1 3

edges

1 1 2 tension 0 sqcurve_string_mark 1 QUANTITY c1_length color blue

2 2 4 tension 0 sqcurve_string_mark 1 QUANTITY c1_length color blue

3 4 3 tension ad/2 sqcurve_string_mark 1+2 QUANTITY c1_length QUANTITY c2_length color red

4 3 1 tension 0 sqcurve_string_mark 1 QUANTITY c1_length color blue

5 4 6 tension 0 sqcurve_string_mark 2 QUANTITY c2_length color blue

6 6 5 tension ad/2 sqcurve_string_mark 2+4 QUANTITY c2_length QUANTITY c3_length color red

7 5 3 tension 0 sqcurve_string_mark 2 QUANTITY c2_length color blue

8 6 8 tension 0 sqcurve_string_mark 4 QUANTITY c3_length color blue

9 8 7 tension 0 sqcurve_string_mark 4 QUANTITY c3_length color blue

10 7 5 tension 0 sqcurve_string_mark 4 QUANTITY c3_length color blue

faces /* edge loop */

1 1 2 3 4

2 -3 5 6 7

3 -6 8 9 10

bodies /* facets */

1 1

2 2

3 3

read

setad:= {set edge tension ad/2 where color == 4 }

setrv:= { set body[1] target (inputrv*pi); set body[2] target (inputrv*pi); set body[3] target (inputrv*pi); }

suml := { La := sum(edges where color == 4,length); La12 := sum(edges where original == 3,length);

La23 := sum(edges where original == 6,length)}

report := { suml; rvt1 := body[1].volume/pi; rvt2 := body[2].volume/pi; rvt3 := body[3].volume/pi;

Ef := sqc_c1.value + sqc_c2.value + sqc_c3.value; Et1 := sqc_c1.value + La12*ad/2;

Et2 := sqc_c2.value + La12*ad/2 + La23*ad/2; Et3 := sqc_c3.value + La23*ad/2 ;

Ea:= ad*La; Et := Ef + ad*La;

printf "adhesion potential is %f, total adhesion length is %f, total energy is %f", ad, La, Et}

c1 := { { g 10; V } 100}

c2 := {r; r; r; {c1}10; r; {c1}10}

c3 := {r; r; r; {c1}10;setrv; {c1}10; r; {c1}10}

// Using the c3 or c2 order, we can obtain the structure with or without volume constraint.

S.3. Surface Evolver code for periodic square structure

Here we show a periodic square structure model which needs to run on the Surface Evolver 2.70s.

```
// Surface Evolver code for periodic square structure.
SPACE_DIMENSION 2
STRING
LINEAR
PARAMETER ad = -4
PARAMETER RDx = 1.8 // period length on x direction
PARAMETER RDy = 1.8 // period length on y direction
PARAMETER inputrv = 0.94
PARAMETER RR = 1/4*(RDx+RDy)/cos(pi/8)

torus
periods
RDx 0
0 RDy

view_matrix
1.0 0 3.65
0 1.0 1.85
0 0 1

define edge attribute sqcurve_string_mark integer
quantity sqc1 energy method sqcurve_string_marked modulus 0.5 global parameter_2 1
quantity sqc2 energy method sqcurve_string_marked modulus 0.5 global parameter_2 2
quantity sqc3 energy method sqcurve_string_marked modulus 0.5 global parameter_2 4
quantity sqc4 energy method sqcurve_string_marked modulus -0.5 global parameter_2 8
method_instance ves_length_1 method edge_length modulus 1
method_instance ves_length_2 method edge_length modulus 2
quantity ves_length fixed = 2*pi method ves_length_1 method ves_length_2

vertices
1 RR*cos(-5*pi/24)-RDx RR*sin(-5*pi/24)
2 RR*cos(-pi/8)-RDx RR*sin(-pi/8)
3 RR*cos(pi/8)-RDx RR*sin(pi/8)
4 RR*cos(5*pi/24)-RDx RR*sin(5*pi/24)
5 RR*cos(19*pi/24) RR*sin(19*pi/24)
6 RR*cos(29*pi/24) RR*sin(29*pi/24)
7 RR*cos(7*pi/24) RR*sin(7*pi/24)-RDy
8 RR*cos(3*pi/8) RR*sin(3*pi/8)-RDy
9 RR*cos(5*pi/8) RR*sin(5*pi/8)-RDy
10 RR*cos(17*pi/24) RR*sin(17*pi/24)-RDy
11 RR*cos(31*pi/24) RR*sin(31*pi/24)
12 RR*cos(41*pi/24) RR*sin(41*pi/24)

edges
1 1 2 * * tension 0 color blue sqcurve_string_mark 1 ves_length_1
2 2 3 * * tension ad/2 color red sqcurve_string_mark 1+2 ves_length_2
3 3 4 * * tension 0 color blue sqcurve_string_mark 1 ves_length_1
4 6 2 * * tension 0 color blue sqcurve_string_mark 2 ves_length_1
5 3 5 * * tension 0 color blue sqcurve_string_mark 2 ves_length_1
6 7 8 * * tension 0 color blue sqcurve_string_mark 4 ves_length_1
7 8 9 * * tension ad/2 color red sqcurve_string_mark 2+4 ves_length_2
8 9 10 * * tension 0 color blue sqcurve_string_mark 4 ves_length_1
9 12 8 * * tension 0 color blue sqcurve_string_mark 2 ves_length_1
10 9 11 * * tension 0 color blue sqcurve_string_mark 2 ves_length_1
11 4 7 - + tension 0 color blue sqcurve_string_mark 1+4+8 ves_length_1
12 5 10 * + tension 0 color blue sqcurve_string_mark 2+4+8 ves_length_1
13 6 11 * * tension 0 color blue sqcurve_string_mark 2 ves_length_1
14 12 1 + * tension 0 color blue sqcurve_string_mark 1+2+8 ves_length_1

faces /* edge loop */
1 1 2 3 11 6 7 8 -12 -5 -2 -4 13 -10 -7 -9 14
```

```

bodies /* facets */
1      1

read
setrv := { set body[1] target (inputrv * pi)}
setad := { set edge tension ad/2 where color == 4}
suml := { La := 2*sum(edges where color == 4,length); Lf := sum(edges where color == 1,length)}
report := { suml;
  rvt := body[1].volume/pi;
  Ef := sqc1.value + sqc2.value+ sqc3.value+ sqc4.value;
  Ea := ad*La/2;
  Et := Ef + Ea;
  printf "ad is %f, La is %f, Lf is %f, Ef is %f, Et is %f, rv is %f", ad, La, Lf, Ef, Et, rvt}
tran2 := { transform_expr "ab"; show_trans "R"; } // twice in each direction
tran3 := { transform_expr "abab"; show_trans "R"; } // three times in each direction
tran4 := { transform_expr "ababab"; show_trans "R"; } // four times in each direction
tran8 := { transform_expr "7(ab)"; show_trans "R"; } // four times in each direction
tran1 := { transform_expr ""; show_trans "R"; } // just the original
c1 := {{g 10; V }200}
c2 := {g;r;{c1}100;r;{c1}100;tran4}
c3 := {g;r;c1;r;setrv;{c1}100;{c1}100;tran4}
//Using the c3 or c2 order we can obtain periodic square structure with or without volume constraint.
//Using the c2 order, we can see that the adhesion regions are straight lines when there is not volume constraint.

```