

Supplementary information

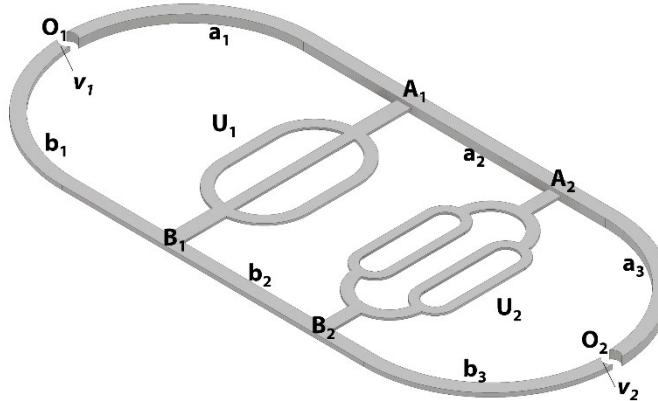


Figure S1. Fluid network of an example multi-channel, multi-unit UniChip. O₁ and O₂ are I/O ports; U₁ with 3 branches and U₂ with 4 branches are two unidirectional channel networks (UCNs); a₁, a₂, a₃, b₁, b₂, and b₃ are supporting channels. R_x is the hydraulic resistance of

$$\frac{R_{a_1}}{R_{b_1}} = \frac{R_{a_2}}{R_{b_2}} = \frac{R_{a_3}}{R_{b_3}}$$

channel x. (by designing channel a_i and b_i to have same length and width but different depth (i=1, 2, or 3)). v₁ and v₂ are one-way valves. v₁ only allows fluid in b₁ flows from B₁ to O₁; v₂ only allows fluid in b₃ flows from B₂ to O₂.

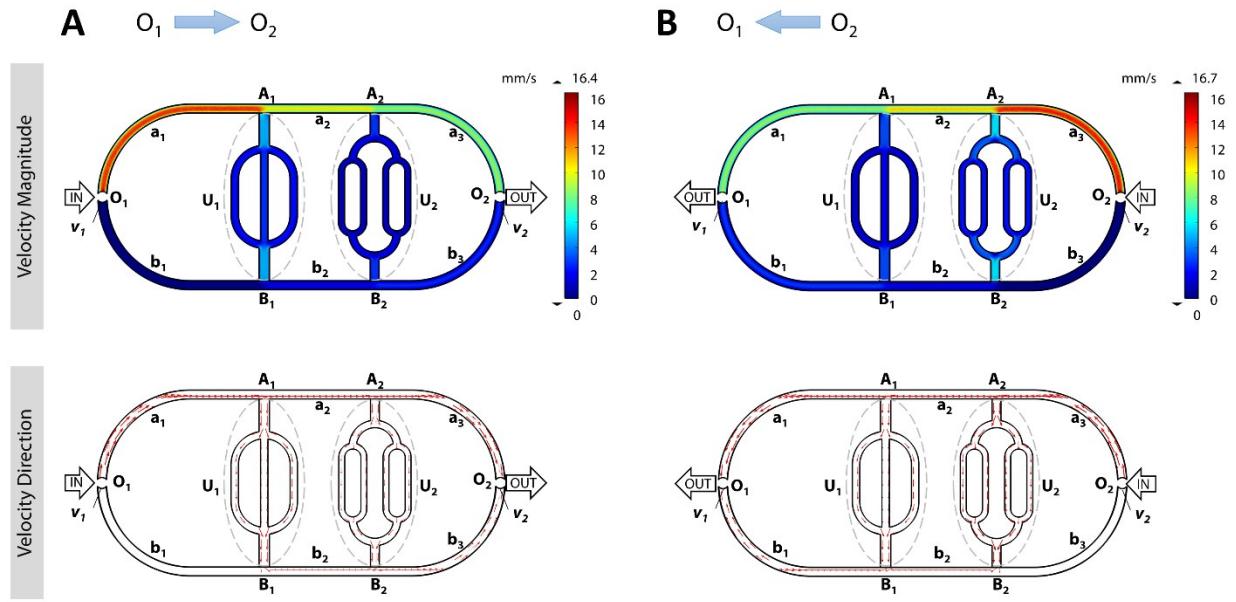


Figure S2. Simulated velocity field (magnitude and direction) of the example multi-channel, multi-unit UniChip (Figure 1) with reciprocating flow input: A) $O_1 \rightarrow O_2$; pressure was set to 30 pa for O_1 and 0 for O_2 for simulation; B) $O_2 \rightarrow O_1$; pressure was set to 30 pa for O_2 and 0 for O_1 ; In both cases, flow in U_1 is from A_1 to B_1 , and flow in U_2 is from A_2 to B_2 (arrows)

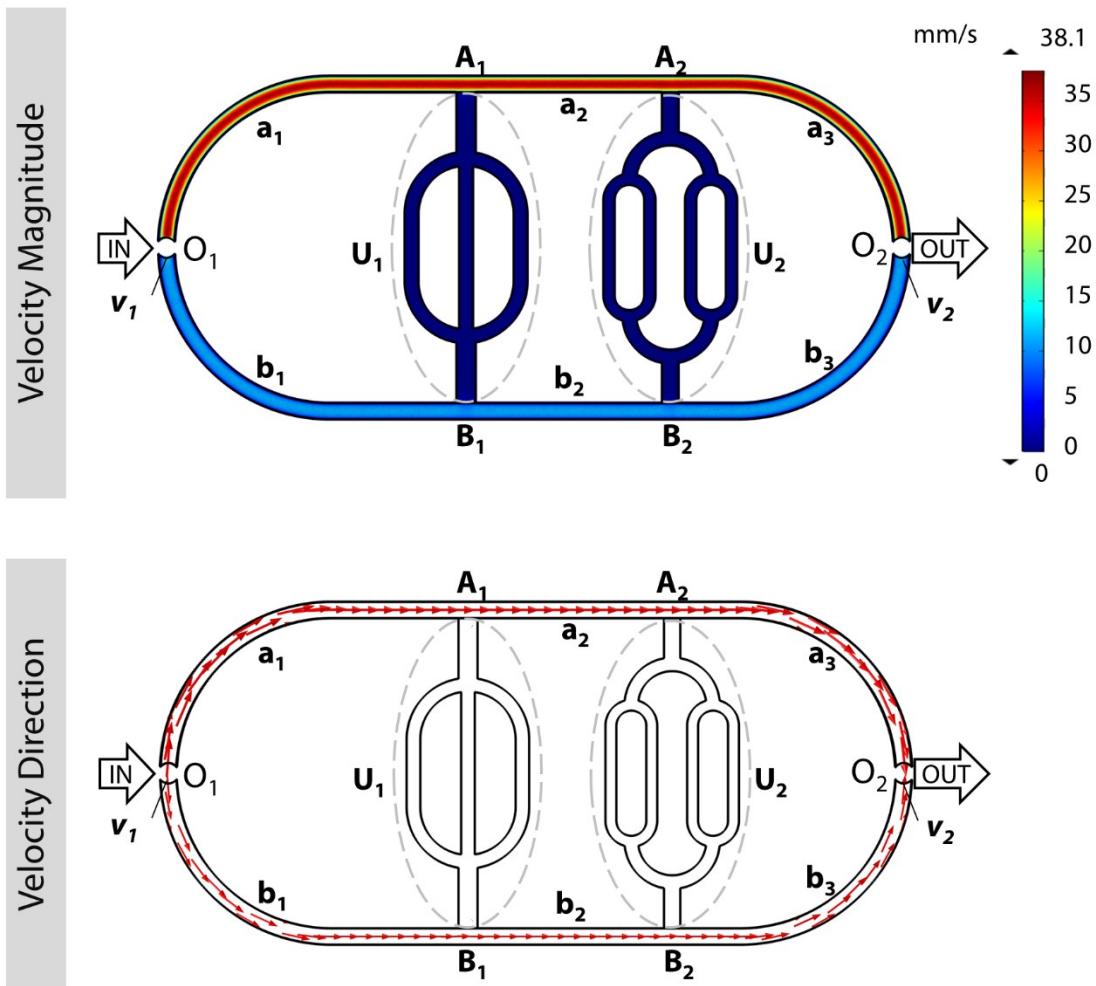


Figure S3. Operation of the backflow proof mechanism in the example multi-channel, multi-unit UniChip when valves fail to limit backflow. Simulated velocity field in the UniChip, when v_1 completely fails to limit backflow (from $O_1 \rightarrow B_1$ through b_1). Fluid flows from O_1 to O_1 through a_1 , a_2 , and a_3 , or through b_1 , b_2 , and b_3 . Flows in U_1 and U_2 approach 0 without changing flow direction.