Gradient in Electric Field for Particle Position Detection in Microfluidic Channels[†]

Lab on a chip Supplementary Information

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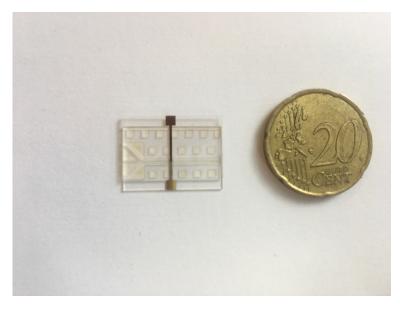


Figure S1 . Microfluidic chip used to track the position of $80\mu m$ particles.

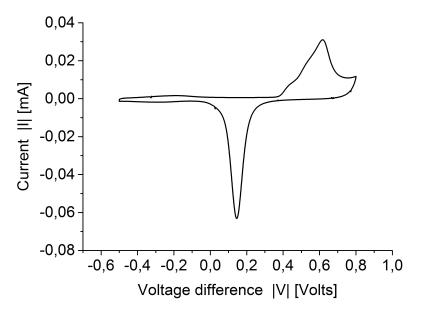


Figure S2 . Cyclic voltammogram of the gold electrodes with exposed regions to be electrodesposited with platinum black in 0.1 M H₂SO₄ solution and a scan rate of 10 mV/s.

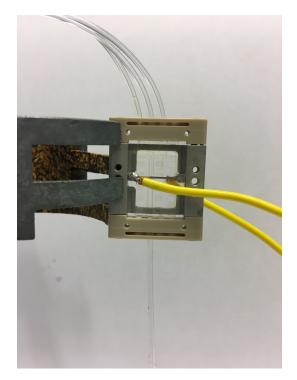
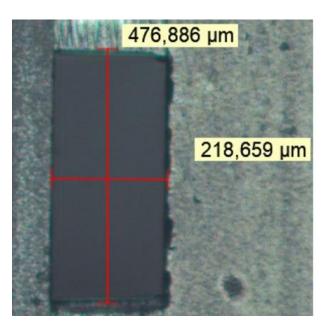


Figure S3 . Microfluidic chip and chip-holder used to measure the position and conductivity of polystyrene particles.



 $\ensuremath{\textit{Figure S4}}$. Dimensions of the microfluidic channel.

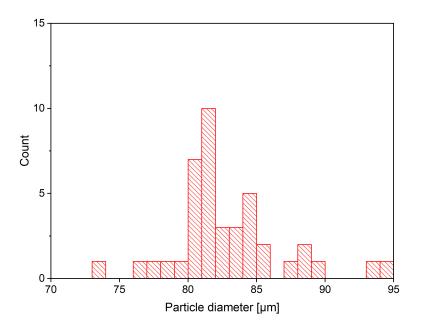


Figure S5 . Histogram of the particle size distribution of 41 polystyrene particles.

$\Lambda 7 -$	<i>PeakHeight</i> * 100	(1)
$\Delta z =$	Totalimpedanceof the system without particles * 100	(1)

Radius (µm)	Frequency (ω)	Impedance (Ω)	Impedance difference with a 37 μm (Ω)
37	100000	721,13	0,00
39	100000	721,75	0,61
41,5	100000	722,60	1,47
44	100000	723,56	2,43
47	100000	724,88	3,74

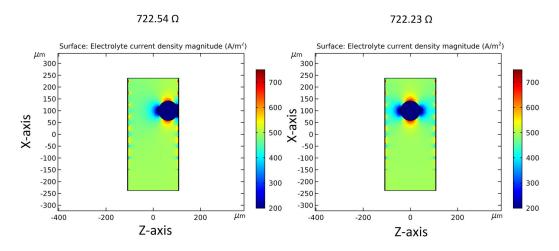


Figure S6 . FEM simulations showing differences in impedance for different z-positions of the particle. X and y-axis are the spatial length in the electrochemical cells.

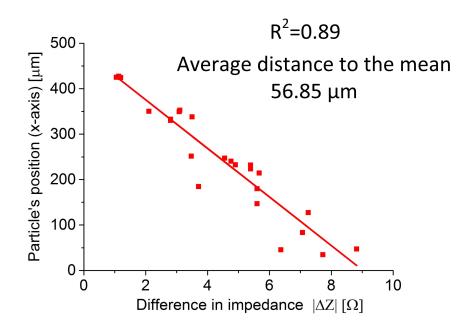


Figure S7 . Linear trendline of the experimental data at 800Hz with R² and average distance of the experimental data to the trendline.