# Electronic Supplementary Information 

# Fast, quantitative and high resolution mapping of viscoelastic properties with bimodal AFM 

Simone Benaglia, Carlos A. Amo and Ricardo Garcia*
Instituto de Ciencia de Materiales de Madrid, CSIC
c/ Sor Juana Ines de la Cruz 3
28049 Madrid, Spain
Email address: r.garcia@,csic.es

## Derivation of Equations 12-14

The virial for the $i$-th mode is calculated by
$V_{i}=f_{i} \int_{0}^{1 / f_{i}} F_{t s}\left(z_{c}+z(t)\right) z_{i}(t) d t$
where the cantilever's deflection is given by
$z(t)=z_{0}+z_{1}(t)+z_{2}(t)$
For an elastic interaction and in the absence of long-range forces, the above integral is calculated in the time interval $\left[t_{a}, t_{b}\right]$ for which $z_{c}+z(t) \leq 0$. By assuming that $z_{0}$ and $A_{2}$ are negligible with respect to $A_{1}$, then the virial of the first mode is given by
$V_{1}=f_{1} \int_{t_{a}}^{t_{b}} F_{t s}\left(z_{c}+z(t)\right) z_{1}(t) d t$
From $t_{a}$ to $t_{b}$, the force increases from zero to its peak force value at $t=t^{*}$ and then it decreases to zero at $t=t_{b}$. Then, if the contact area is kept constant during approach and retraction
$V_{1}=f_{1} \int_{t_{a}}^{t_{b}} F_{t s}\left(z_{c}+z(t)\right) z_{1}(t) d t=2 f_{1} \int_{t_{a}}^{t^{*}} F_{t s}\left(z_{c}+z(t)\right) z_{1}(t) d t$
The above integral can be performed in the $z$ domain by using the following change of variables $u=A_{1} \cos \left(\omega_{1} t+\varphi_{1}\right)$
with
$d u=-A_{1} \omega_{1} \sin \left(\omega_{1} t+\varphi_{1}\right)=-\omega_{1} \sqrt{A_{1}^{2}-u^{2}} d t$
then
$V_{1}=\frac{-2}{\omega_{1}} f_{1} \int_{z_{c}}^{A_{1}} F_{t s}\left(z_{c}+u\right) \frac{u}{\sqrt{A_{1}^{2}-u^{2}}} d u$
The indentation can be expressed in terms of the instantaneous deflection as
$\delta(z)=\left\{\begin{array}{lr}0, & z_{1}<z \\ u-z_{c}, & z_{1} \geq z_{c}\end{array}\right.$
for $u=A_{1}$ we reach the maximum indentation (deformation)

$$
\begin{equation*}
\delta_{\max }=A_{1}-z_{c} \tag{S9}
\end{equation*}
$$

The above definitions and the fact that the force is only non-zero when $\delta \neq 0$, enable to express $V_{1}$ as
$V_{1}=\frac{1}{\pi} \int_{0}^{\delta_{m g x}} F_{t s}(\delta) \frac{\delta+z_{c}}{\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}} d \delta$
Now, we introduce the following definitions
$F_{t s}(\delta)=v$
$\frac{d F_{t s}}{d \delta} d \delta=k_{t s}(\delta) d \delta=d v$
$d w=\frac{\delta+z_{c}}{\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}} d \delta$
which implies that
$w=-\frac{\left(\delta+z_{c}+A_{1}\right)\left(-\delta-z_{c}+A_{1}\right)}{\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}}=\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}$
By applying the integration by parts relationship $\int u d v=u v-\int v d u, V_{1}$ becomes
$V_{1}=\frac{1}{\pi}\left(F(\delta) \sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}\right)^{\delta_{\max }}-\frac{1}{\pi} \int_{0}^{\delta_{\operatorname{mgx}}} k_{t s}(\delta) \sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}} d \delta$
The first term is equal to 0 for both extremes of the integration because $F(\delta)=0$ when $\delta=0$, and $A_{1}-z_{c^{\prime}} \sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}=0$ for $\delta=\delta_{\max }$
which leads to
$V_{1}=-\frac{1}{\pi} \int_{0}^{\delta_{m g x}} k_{t s}(\delta) \sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}} d \delta$
Now we can use the definition of the maximum indentation (equation S9) to replace zc in the above equations,
$\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}=\sqrt{A_{1}^{2}-\left(\delta+A-\delta_{\max }\right)^{2}}=A_{1} \sqrt{1-\left(1-\frac{\delta_{\max }-\delta}{A_{1}}\right)^{2}}$
when the deformation is small respect to the amplitude $A_{1}$,
$x=\frac{\delta_{\max }-\delta}{A_{1}} \ll 1$
we can apply series expansion
$\sqrt{1-(1-x)^{2}} \approx \sqrt{2 x}-\frac{1}{4} \sqrt{2 x^{3}}-\frac{1}{32} \sqrt{2 x^{5}} \ldots$

By keeping the first term, an approximation that is valid with the amplitudes and deformations used in bimodal AFM, Eq. S17 becomes
$A_{1} \sqrt{1-\left(1-\frac{\delta_{\max }-\delta}{A_{1}}\right)^{2}} \approx \sqrt{2 A_{1}} \sqrt{\delta_{\max }-\delta}$
Then equation S16 becomes
$V_{1} \approx-\frac{1}{\pi} \int_{0}^{\delta_{\operatorname{mgx}}} k_{t s}(\delta) \sqrt{2 A_{1}} \sqrt{\delta_{\max }-\delta} d \delta$
which corresponds to equation 12 (main text).
Now we proceed to calculate virial of the second mode. From equations 4 and 7 (main text) we get,
$V_{2}=-\frac{k_{2} A_{2}^{2} \Delta f_{2}}{f_{02}}=\left(A_{2}^{2} / 4 \pi\right) \int_{0}^{1 / f_{1}} F_{t s}{ }^{\prime}(t) d t$
$\frac{\Delta f_{2}}{f_{02}} \approx-\frac{1}{4 \pi k_{2}} \int_{0}^{1 / f_{1}} k_{t s}(t) d t$
It is more convenient to perform the integral in ${ }^{z}$ domain. To that purpose we use the definitions given in equations S4 and S5,
$\frac{\Delta f_{2}}{f_{02}} \approx \frac{1}{4 \pi k_{2}} 2 \int_{z_{c}}^{A_{1}} k_{t s}(u) \frac{d u}{\sqrt{A_{1}^{2}-u^{2}}}$
which in terms of the indentation ( $\delta=u-z_{c}$ )
$\frac{\Delta f_{2}}{f_{02}} \approx \frac{1}{2 \pi k_{2}} \int_{0}^{\delta_{\operatorname{mgx}}} k_{t s}(\delta) \frac{d \delta}{\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}}$
Then equation S 22 becomes
$V_{2} \approx-\frac{A_{2}^{2_{2}}}{2 \pi} \int_{0}^{m g x} k_{t s}(\delta) \frac{d \delta}{\sqrt{A_{1}^{2}-\left(\delta+z_{c}\right)^{2}}}$
by using equation S20
$V_{2} \approx-\frac{A_{2}^{2}}{2 \pi} \int_{0}^{\delta_{m g x}} k_{t s}(\delta) \frac{d \delta}{\sqrt{2 A_{1}} \sqrt{\delta_{\max }-\delta}}$
This step finalizes the deduction of equation 13 (main text).
Now we proceed to derive equation 14 (main text). We start from the definition of the energy dissipation (equation 5)
$E_{d i s i}=-\int_{0}^{1 / f_{i}} F_{t s}(t) \dot{z}_{i}(t) d t$
we define a dissipative force as
$F_{\text {dis }}=\Lambda(z) \dot{z}(t)$
where $\Lambda(z)$ is a dissipation function.
by using the definition of $u$ (equations S 5 and S6),
$d t=\frac{d u}{-\omega_{1} \sqrt{A_{1}^{2}-u^{2}}}$
Then the energy dissipated for the first mode:
$E_{d i s 1}=\int_{-A_{1}}^{A_{1}} \Lambda\left(z_{c}+u\right)\left(-\omega_{1} \sqrt{A_{1}^{2}-u^{2}}\right)^{2} \frac{d u}{-\omega_{1} \sqrt{A_{1}^{2}-u^{2}}}=$
$-\int_{-A_{1}}^{A_{1}} \Lambda\left(z_{c}+u\right) \omega_{1} \sqrt{A_{1}^{2}-u^{2}} d u$
by using
$\sqrt{A_{1}^{2}-u^{2}}=\int \frac{-u}{\sqrt{A_{1}^{2}-u^{2}}} d u$
and the definitions
$v=\sqrt{A_{1}^{2}-u^{2}} ; d v=\frac{-u}{\sqrt{A_{1}^{2}-u^{2}}} d u$
$d w=\Lambda\left(z_{c}+u\right) d u ; \quad w=M(u)=\int d u \Lambda\left(z_{c}+u\right)$
we apply the integration by parts formula

$$
\begin{equation*}
\int_{-A}^{A} \Lambda\left(z_{c}+u\right) \sqrt{A_{1}^{2}-u^{2}} d u_{1}=\sqrt{A_{1}^{2}-u^{2}} M(u)-\int_{-A_{1}}^{A_{1}} M(u) \frac{-u}{\sqrt{A_{1}^{2}-u^{2}}} d u \tag{S35}
\end{equation*}
$$

The first term is zero, then the energy dissipated by mode 1 is
$E_{d i s 1}=-\omega_{1} \int_{-A_{1}}^{A_{1}} \Lambda\left(z_{c}+u\right) \sqrt{A_{1}^{2}-u_{1}^{2}} d u_{1}=\omega_{1} \int_{-A_{1}}^{A_{1}} M(u) \frac{u}{\sqrt{A_{1}^{2}-u^{2}}} d u$
, which resembles equation $S 10$, then by analogy we deduce
$E_{\text {dis1 }}=2 \int_{0}^{\delta_{\text {mgx }}} g_{\text {int }}(\delta) \sqrt{2 A_{1}} \sqrt{\delta_{\text {max }}-\delta^{\prime}} d \delta$
where $g_{\text {int }}$ is the dissipative equivalent of $k_{\text {int }}$ in a conservative interaction force.

## Calibration of bimodal AM-FM

The value of the Young's modulus given by bimodal AM-FM has been determined with a calibrated polystyrene sample of Young's modulus $=2.7 \mathrm{GPa}$ (Bruker Test Sample). For completeness we provide the viscosity coefficient, the loss tangent and the retardation time.

Figure S1. (a) Young's modulus, (b) viscous coefficient, (c) loss tangent and (d) retardation time on a PS sample of nominal elastic modulus value of 2.7 GPa . The Young's modulus has been calculated considering a $v_{\mathrm{s}}=0.34$. (e) The extracted nanomechanical values are shown. The measurement parameters are $A_{01}=81 \mathrm{~nm}, A_{1}=65 \mathrm{~nm}, f_{01}=68.070 \mathrm{kHz}, k_{1}=2.77 \mathrm{~N} \mathrm{~m}^{-1}, Q_{1}=$ $208, A_{2}=1.2 \mathrm{~nm}, f_{02}=432.333 \mathrm{kHz}, k_{2}=142 \mathrm{~N} \mathrm{~m}^{-1}, R=12 \mathrm{~nm}$.


| $E(\mathrm{GPa})$ | $\tan \rho$ | $\tau(\mu \mathrm{s})$ | $\eta_{\mathrm{com}}(\mathrm{Pa} \mathrm{s})$ |
| :--- | :--- | :--- | :--- |
| $2.75 \pm 0.16$ | $0.028 \pm 0.009$ | $0.06 \pm 0.02$ | $204 \pm 73$ |

## Energy dissipation map of a LDPE sample

Figure S2. Energy dissipation map of the $1^{\text {st }}$ mode on LDPE. The map was acquired simultaneously with the data shown in Fig. 4.


## Influence of the humidity on the bimodal AFM data

Nanomechanical parameters extracted from two bimodal AM-FM experiments performed on a PS-b-PMMA sample with humid air $(\mathrm{RH}=22 \%)$ and in a dry $\mathrm{N}_{2}$ atmosphere ( $\mathrm{RH}<3 \%$ ).

Table S1. PS-b-PMMA viscoelastic properties at two relative humidity.

| Measurement <br> condition | PS-b-PMMA block | $E_{\text {eff }}(\mathrm{GPa})$ | $\tan \rho$ | $\tau(\mu \mathrm{s})$ | $\eta_{\text {eff }}(\mathrm{Pa} \mathrm{s})$ |
| :---: | :--- | :--- | :--- | :--- | :--- |
| Air | PS | $2.1 \pm 0.25$ | $0.11 \pm 0.02$ | $0.22 \pm 0.03$ | $460 \pm 65$ |
|  | PMMA | $2.6 \pm 0.30$ | $0.07 \pm 0.02$ | $0.15 \pm 0.03$ | $350 \pm 65$ |
|  | PS | $2.1 \pm 0.2$ | $0.09 \pm 0.03$ | $0.19 \pm 0.06$ | $423 \pm 130$ |
|  |  | PMMA | $2.6 \pm 0.2$ | $0.03 \pm 0.02$ | $0.07 \pm 0.05$ |
|  |  |  | $200 \pm 120$ |  |  |

