## **Supporting Information**

## Magnetic biohybrid micromotors with high maneuverability for efficient drug loading and controlled release

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**Video S1**. Magnetic propulsion of an individual micromotor in three motion modes (i.e., rolling, spinning and tumbling).

**Video S2**. Programmable navigated locomotion of individual micromotor in the bright and fluorescence mode.

Video S3. Multiple micromotors swimming as a team and controllable swarm locomotion.

**Video S4**. Controllable rotation of magnetic agglomerate inside the air sac by regulating the input magnetic field.



Figure 1. 3D AFM images of the hollow air sac surface of OPP and DPP.



**Figure 2.** The whole process of dissolution of gastric-soluble capsules containing PPBM in the SGF media. And the released PPBM still keep stable morphology. Scar bar, 10 mm.



**Figure 3.** Time-lapse images displaying the navigated locomotion of free PPBM (left) and released PPBM from gastric-soluble capsule (right) in SGF. Scar bars, 50  $\mu$ m.



Figure 4. Comparison of the average velocities of free and released PPBMs in SGF at 25, 31 and 37 °C.



Figure 5. Control cell images without DOX-loaded PPBM. Scar bars, 50  $\mu$ m.