

Fig.S1 The image of undenatured type II collagen with transmission electron microscope



Fig. S2 The infrared spectroscopy of undenatured type II collagen

Amino acid	Content (g/100g)	Amino acid	Content (g/100g)
Asp	4.15	Val	2.05
Glu	8.72	Met	1.15
Ser	1.36	Phe	1.50
His	0.60	Ile	1.32
Gly	11.72	Leu	2.72
Thr	1.81	Lys	2.15
Arg	4.95	Pro	3.63
Ala	4.6	Hydroxyproline	8.26
Tyr	0.46		

Table S1 Amino acid composition of UC  ${\rm I\!I}$ 

Parameter	Definition	
Run Characterization		
Cadence (steps/sec)	Steps per second.	
Temporal Parameters		
Stand or Stance phase (sec)	Duration of contact of a paw with the glass plate.	
Swing or Swing phase (sec)	Duration of no contact of a paw with the glass.	
	Time between two consecutive initial contacts of the same	
Step Cycle (sec)	paw.	
Duty Cycle (%)	Relative Stand Phase as part of Step Cycle.	
	Duration of contact with the glass for a single hind paw.	
Cincle Otenner (core)	In others words, duration of a Step Cycle in which one	
Single Stance (sec)	paw is in contact with the glass plate, but the contralateral	
	paw is not.	
Spatial Parameters		
Max Contact Max Intensity (a.u)	Maximum intensity at max contact of a paw.	
Mean Intensity (a.u)	Mean intensity of the complete paw.	
Kinetic Parameters		
Swing Speed (cm/s)	Speed of the paw during Swing.	
Interlimb Coordination Parameters		
Stride Length (cm)	Distance between successive placements of the same paw.	
Ston Soguenee	Order in which the paws were placed on the glass plate.	
Step Sequence	This order determines the footfall pattern.	
	Regularity Index (RI) parameter expresses the number of	
StepSequence_RegularityIndex_(%)	normal step sequence patterns relative to the total number	
	of paw placement.	
	The moment of initial contact of a target paw expressed as	
Phase Dispersion %	a percentage of the Step Cycle time of an anchor paw	
	(Ranges from 75 to -50%).	
	Percentage of a run when the animal is supported by one,	
Support (%)	two three or four paws simultaneously on the glass plate	
	in each Step Cycle.	
	Two paws in contact with the glass plate divided in three	
Support_Diagonal_(%)	categories: Girdle: Either front or hind paws.	
Support_Girdle_(%)	Lateral: Either left or hind paws.	
Support_Lateral_(%)	Diagonal: either Right Front + Left Hind or Left Front +	
	Right Hind.	
Support_Three_(%)	Three paws in contact with the glass plate.	

## Table S2. The description of gain parameters