## **Supporting Information**

## **Interpenetrating PAA-PEDOT Conductive Hydrogels for**

## **Flexible Skin Sensors**

Fanfan Fu,<sup>1</sup> Jilei Wang,<sup>1</sup> Jing Yu\*<sup>1</sup>

<sup>1</sup>School of Materials Science and Engineering, Nanyang Technological University, 639798,

Singapore. \*E-mail: yujing@ntu.edu.sg (J. Yu)



**Fig. S1**. The images of PAA-PEDOT hydrogels with different PAA concentrations. From left to right, the concentrations of PAA were 15% (wt.), 30% (wt.), and 45% (wt.), respectively.



Fig. S2. Adhesion force of PAA hydrogel on human skin, glass substrate, and metal (iron) substrate.



**Fig. S3**. SEM images of PAA and PAA-PEDOT hydrogels. (a) SEM image of the surface of a PAA hydrogel. (b-d) SEM image of the surface of PAA-PEDOT hydrogels with different electronical deposition times. From left to right, the electronical deposition times were 1 min, 5 min, and 10 min, respectively.



Fig. S4. Schematic of the generation process of crumpled rGO/Pt template.



Fig. S5. The selectivity performances of K<sup>+</sup> sensor in different ionic solution.



**Fig. S6**. The stability performances of the PAA-PEDOT-based sensors in Na<sup>+</sup> (50 mM, 120 mM) and K<sup>+</sup> (5 mM, 8 mM) ionic solution for 30 min.



**Fig. S7**. The multicycle stability performances of the PAA-PEDOT-based sensors in Na<sup>+</sup> (50 mM, 120 mM) and K<sup>+</sup> (5 mM, 8 mM) ionic solution for 2 hours.