

Supporting Information

A new insight into ZIF-67 based triboelectric nanogenerator for self-powered robot object recognition

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Figure S1: Simulated XRD pattern of ZIF-67 particle.

Figure S2: Surface micrographs of bare copper electrode and ZIF-67 firmly attached upon copper electrode.

Figure S3: Wavelet transformation of the S-TENG signals generated from the gaits of the seven volunteers.

Table S4: Comparison of the electrical output of the MOF based TENG devices.

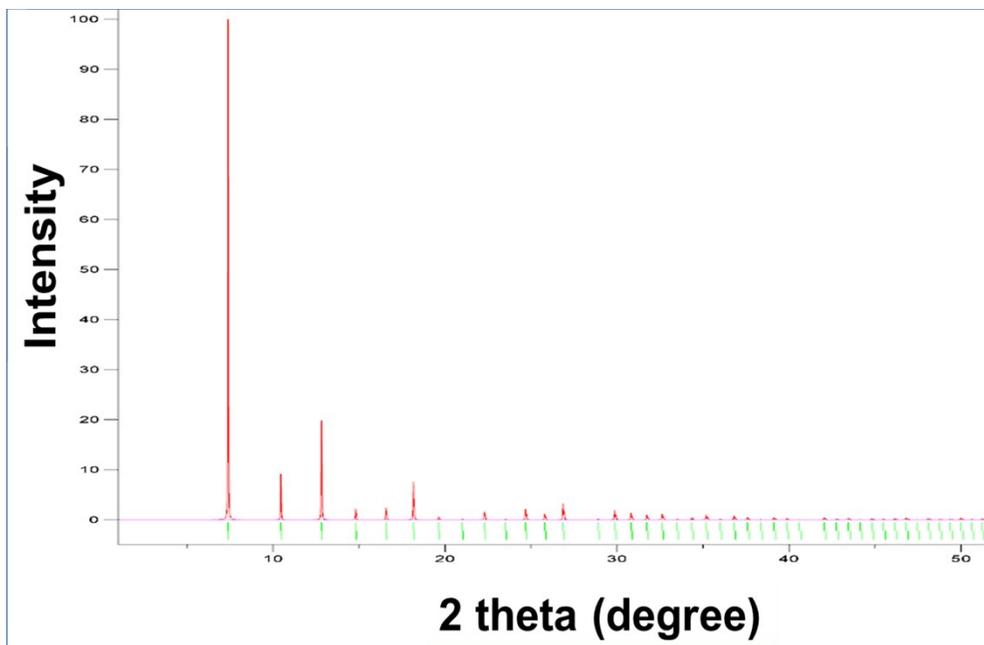


Figure S1

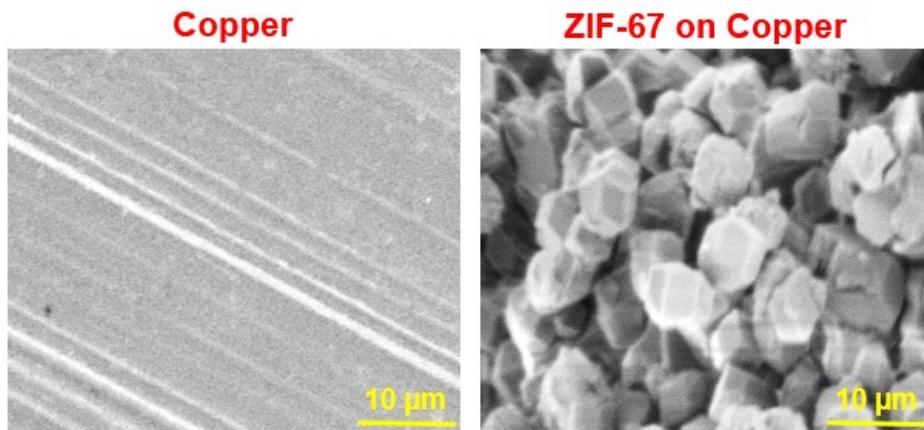


Figure S2

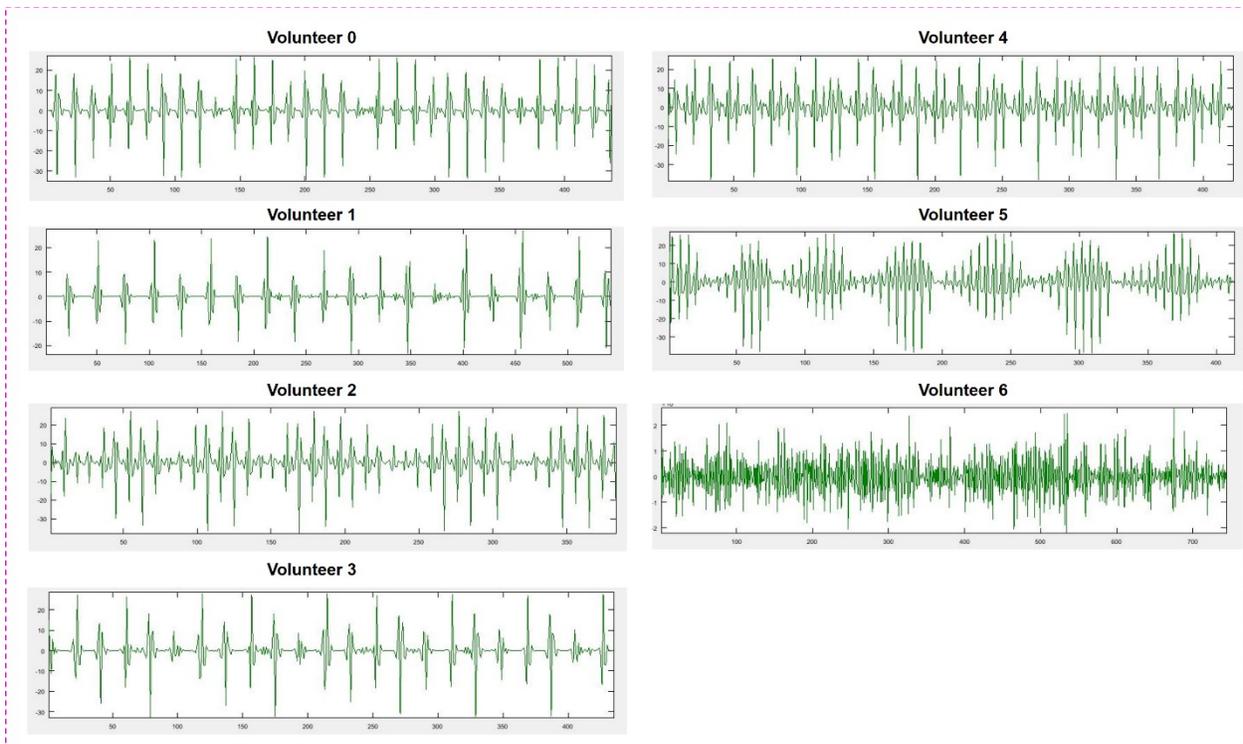


Figure S3

Table S4

Positive layer	Negative layer	Voltage (V)	Working Mode	Ref
ZIF-11	Kapton	27	Contact separate	1
ZIF-12	Kapton	42	Contact separate	1
ZIF-9	Kapton	29	Contact separate	1
ZIF-7	Kapton	60	Contact separate	1
ZIF-62	Teflon	62	Contact separate	2
ZIF-67	Teflon	118	Contact separate	This Work

References:

[1] G. Khandelwal, N.P. Maria Joseph Raj, S.-J. Kim, *Advanced Functional Materials*, 30 (2020) 1910162.

[2] G. Khandelwal, N.P. Maria Joseph Raj, S.-J. Kim, *Journal of Materials Chemistry A*, 8 (2020) 17817-17825.