Electronic Supplementary Information

Phototactic Micromotor Assemblies in Dynamic Line Formations for

Wide-Range Micromanipulations

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Experimental Section

Materials

Anhydrous ethanol (CH₃CH₂OH), tetrabutyl titanate (C₁₆H₃₆O₄Ti), hydrogen peroxide solution (H₂O₂), ethylene glycol(C₂H₆O₂) were purchased from Sinopharm Chemical Reagent Co., Ltd. (China). All chemicals were all of the analytic grades and were used without further purification. Hydroxyl Magnetic Beads (500 nm) were purchased from Suzhou Nano-Micro Technology Co., Ltd. (Suzhou, China). Polystyrene (PS) microspheres (5 μ m) were purchased from Aladdin-Holdings Group.

Fabrication of MB@TiO₂ MMs

The MB@TiO₂ MMs were synthesized by an ultrasonic-assisted sol-gel method. At first, a 176 μ L tetrabutyl titanate and 5 mL ethylene glycol were mixed and magnetically stirred for 10 min. Then, a 5 mL ethanol suspension of magnetic beads (MBs, 2 mg mL⁻¹) was added to the above solution and sonicated for 20 min in an ultrasonic cleaner (Sumei KQ2200, China). After being collected by magnetic separation and washed three times with deionized water and absolute ethanol, MB@amorphous TiO₂ core-shell microparticles (MB@A-TiO₂ MPs) were obtained. Finally, the MB@A-TiO₂ MPs were calcined at 550 °C for 2 h to obtain the MB@TiO₂ MMs.

Characterization

Scanning electron microscopy (SEM) images were obtained using a Hitachi S-4800 field-emission SEM (Japan). Transmission electron microscopy (TEM) images were obtained using a High-resolution Transmission Electron Microscope (JEM-1400Plus, Japan). The zeta potential of the MMs was obtained by NanoBrook 90 Plus Zeta (US). An X-ray photoelectron spectroscopy (XPS) (Thermo Scientific ESCALAB 250Xi, USA) was employed to characterize the XPS spectra of Ti 2p on the MB@TiO₂ MMs. The magnetization hysteresis loop of the MB@TiO₂ MMs was acquired by a vibrating sample magnetometer (LakeShore 7404, USA) at room temperature. A digital Tesla meter (YF-801EXP, China) was used to measure the intensity of the applied magnetic field.

Phototactic flocking behaviors and cooperative large-cargo manipulations

A 65 μ L of the aqueous suspension of MB@TiO₂ MMs (0.4 mg mL⁻¹) and a 65 μ L of H₂O₂ solution (5 wt.%) were dropped onto a clean glass slide and covered with a cover glass. UV lamps with a wavelength of 365 nm and intensity (I) of 0.41 W cm⁻² (SZ Lamplic Technology) were used as the sidewise light sources, which were set above the substrate and irradiated downward with an oblique incident angle of 30°. The UV light from the built-in Leica EL6000 light source of an inverted optical microscope (Leica DMI 3000B, Germany) was used as the vertical light source (UV_z, I = 0.51 W cm⁻²) to avoid floating up of the MMs. A permanent magnet was placed next to the slide to provide a static magnetic field (H). The assembly/disassembly and phototactic flocking behaviors of the MB@TiO₂ MMs were investigated by controlling the on/off states, directions and intensity of the sidewise light sources and the applied H. The PS microspheres with a size of 5 μ m were used as large cargoes to investigate their cooperative large-cargo manipulations. Micropatterned glass chips with rectangular prism obstacles, Y-shaped branched microchannels or dumbbell-shape microchannels were used to investigate the phototactic flocking behaviors and cooperative largecargo manipulations of the MB@TiO2 MMAs in complex microenvironments. All videos were recorded at room temperature by an inverted optical microscope (Leica DMI 3000B, Germany) and analyzed by using ImageJ and Video Spot Tracker V08.01 software.

Numerical simulation

The simulations were performed by using the diffusions, electrostatics and creeping flow modules of COMSOL Multiphysics software.¹ In the simulation, a two-dimensional (2D) model was built up by placing an MB@TiO₂ MMA in the middle of a cuboid cell (20×20 µm) filled with water. The release and consumption rate of H⁺ on the illuminated and shadowed surface of the MB@TiO₂ MMA was set to be 1×10^{-8} mol m⁻² s⁻¹, respectively. The diffusion coefficient (D) of H⁺ and OH⁻ was set to be 9.31×10^{-9} and 5.27×10^{-9} m² s⁻¹. The electroosmotic-flow boundary conditions were set at the charged surfaces of the MB@TiO₂ MMA and the glass substrate (the bottom edge of the cell). The zeta potential ζ_p of the MB@TiO₂ MMA was set to be -53.8 mV according to the result of the zeta potential test, and that of the glass substrate (ζ_w) was set to be -85 mV.²

Supplementary Figures



Fig. S1 The SEM image of pristine MBs. Scale bar, 500 nm.



Fig. S2 The zeta potential of the MB@TiO₂ MMs.



Fig. S3 SEM images of the MB@TiO₂ MMAs formed under the magnetic field with an intensity of 20 (A, B) and 50 Oe (C, D). Scale bars in A and B are 5 μ m and 500 nm, respectively. Scale bars in C and D are 5 μ m.



Fig. S4 Schematic illustration of the experimental devices with (A) a single sidewise UV light and (B) with the superimposed sidewise and vertical (UV_z) lights. UV_x represents the horizontal projection of the incident sidewise UV light on the substrate.



Fig. S5 Time-lapse microscopic images depicting the floating of the MB@TiO₂ MMAs during phototaxing under a single sidewise UV light (without UV_z). The *I* of the sidewise UV light and $C_{\rm f}$ are 0.16 W cm⁻² and 2.5 wt.%, respectively. Scale bar, 50 µm.



Fig. S6 The *U* of the MB@TiO₂ MMAs with different lengths (*L*). The *I* of the sidewise UV light and $C_{\rm f}$ in this experiment are 0.41 W cm⁻² and 2.5 wt.%, respectively.



Fig. S7 Time-lapse microscopic images illustrating the deformation and phototactic motion of a typical MB@TiO₂ MMA formed under the external *H* with a high intensity of 50 Oe, revealing that it can not disassemble into dispersed motors after the *H* is removed. The *I* of the sidewise UV light and $C_{\rm f}$ in this experiment are 0.41 W cm⁻² and 2.5 wt.%, respectively. Scale bar, 10 µm.



Fig. S8. Numerical simulations of (A) the $[H^+]$ increment ($\Delta[H^+]$) and (B) the electric potential (*V*) around an MB@TiO₂ MMA in the *x-z* plane. Black triangles in B represent the direction of the local electric field (*E*).



Fig. S9. (A-C) Trajectories of MB@TiO₂ MMAs with different ϑ of 0° (A), 27° (B) and 43° (C), respectively, depicting their increasing migration angle with ϑ . (D) The normalized speed of the MB@TiO₂ MMAs as a function of ϑ . Scale bars in A-C, 10 µm.

Supplementary Videos

Video S1. Dynamic assembly/disassembly behaviors and phototactic flocking of the $MB@TiO_2$ MMs in response to the external *H* and the sidewise UV irradiation.

Video S2. Floating of the MB@TiO₂ MMAs when phototaxing under an oblique downward UV light.

Video S3. Phototactic flocking of the MB@TiO₂ MMAs at different C_f.

Video S4. Phototactic flocking of the MB@TiO₂ MMAs at different *I*.

Video S5. Phototactic motions of single MB@TiO₂ MMs and MB@TiO₂ MMAs.

Video S6. Phototactic flocking of the MB@TiO₂ MMAs with different φ of the failed individuals.

Video S7. Phototactic flocking of a typical MB@TiO₂ MMA along a predesigned path by adjusting its ϑ .

Video S8. Phototactic flocking of the MB@TiO₂ MMAs when bypassing a rectangular-prism obstacle utilizing their dynamic assembly/disassembly behaviors.

Video S9. Phototactic flocking of the MB@TiO₂ MMAs when passing through the Y-shape branched microchannels utilizing their dynamic assembly/disassembly behaviors.

Video S10. Phototactic flocking of the $MB@TiO_2$ MMAs when passing through a dumbbell-like microchannel by changing their orientations.

Video S11. Cooperative transport of a large PS microsphere (5 μ m) by the MB@TiO₂ MMAs in an open area.

Video S12. Cooperative transport of a large PS microsphere (5 μ m) by the MB@TiO₂ MMAs in a confined microchannel.

Video S13. Phototactic flocking of the MB@TiO₂ MMAs when carrying different numbers of the PS microspheres.

Video S14. Sweeping of the PS microspheres (as solid "wastes") out of a specific region by the $MB@TiO_2 MMAs$.

References

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