Levitons and anti-levitons in graphene

By D. M. Forrester and F. V. Kusmartsev

Supporting information to the main text

The following describes the animations that accompany the text.

Animation 1:

This animation supports Fig. 3 of the main text. It describes the case when $\alpha = 0.4$ and the applied field is B = 5mT.

Animation 2:

This animation supports Fig. 4 of the main text. It describes the case when $\alpha = 0.4$ and the applied field is B = 2.5T.

Animation 3:

This animation supports Fig. 5 of the main text. It describes the case when $\alpha = 0.4$ and the applied field is B = 6.5T. The levity vortex can be seen.

Animation 4:

This animation supports Fig. 7 (a) of the main text. It describes the case when $\alpha = 1$ and the applied field is B = 5mT.

The next series of animations are for when the energy of the Leviton is constant and the step potential is changed each time, with B=5mT.

Animation 5: $\alpha = 5/2$ Animation 6: $\alpha = 5/3$ Animation 7: $\alpha = 5/4$ Animation 8: $\alpha = 5/5$ Animation 9: $\alpha = 5/6$ Animation 10: $\alpha = 5/8$ Animation 11: $\alpha = 5/10$ Animation 12: $\alpha = 5/12$ Animation 13: $\alpha = 5/20$