

ELECTRONIC SUPPLEMENTARY INFORMATION

Fabrication and analysis of enforced dry adhesives with core-shell micropillars

Won-Gyu Bae,^{a,b} Moon Kyu Kwak,^c Hoon Eui Jeong,^d Changhyun Pang,^b Hakgeun Jeong^e

and Kahp-Yang Suh*,^{a,b}

^a Interdisciplinary Program of Bioengineering, Seoul National University, Gwanak_1, Gwanak-ro, Gwanak-gu, Seoul 151-742, Korea. Fax: +82-2-883-0179; Tel: +82-2-880-9103; E-mail: sky4u@snu.ac.kr

^b School of Mechanical and Aerospace Engineering, Seoul National University, Seoul 151-742, Korea.

^c School of Mechanical Engineering, Kyungpook National University, Daegu 702-701, Korea.

^d School of Mechanical and Advanced Materials Engineering, Ulsan National Institute of Science and Technology, Ulsan 689-798, Korea.

^e Energy Efficiency Research Division, Korea Institute of Energy Research, 152 Gajeong-ro, Yuseong-gu, Daejeon 305-343, Korea.

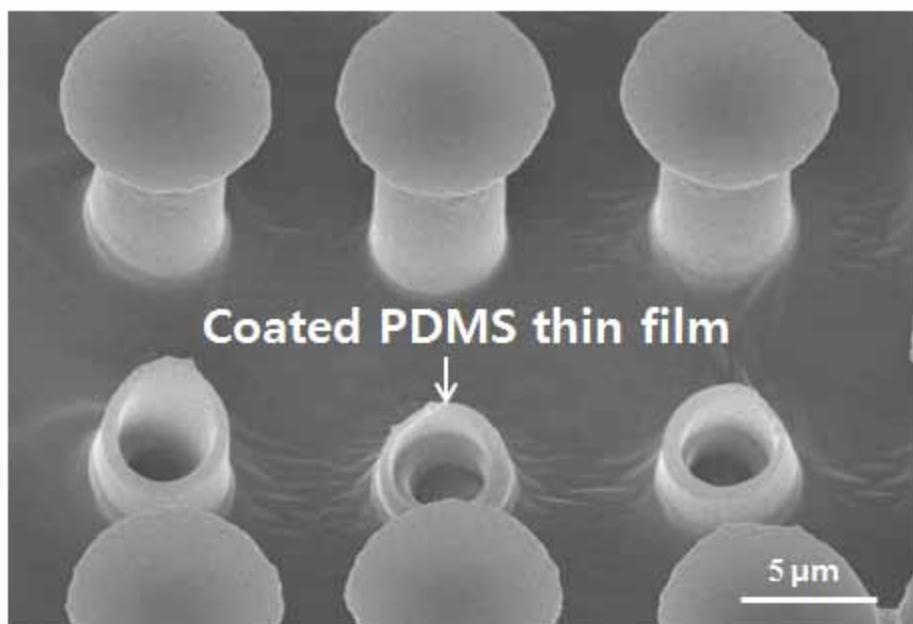


Fig S1. SEM image showing the effect of plasma treatment on the stability of core-shell micropillars. Without the treatment, local delaminations were frequently observed with repeated uses.

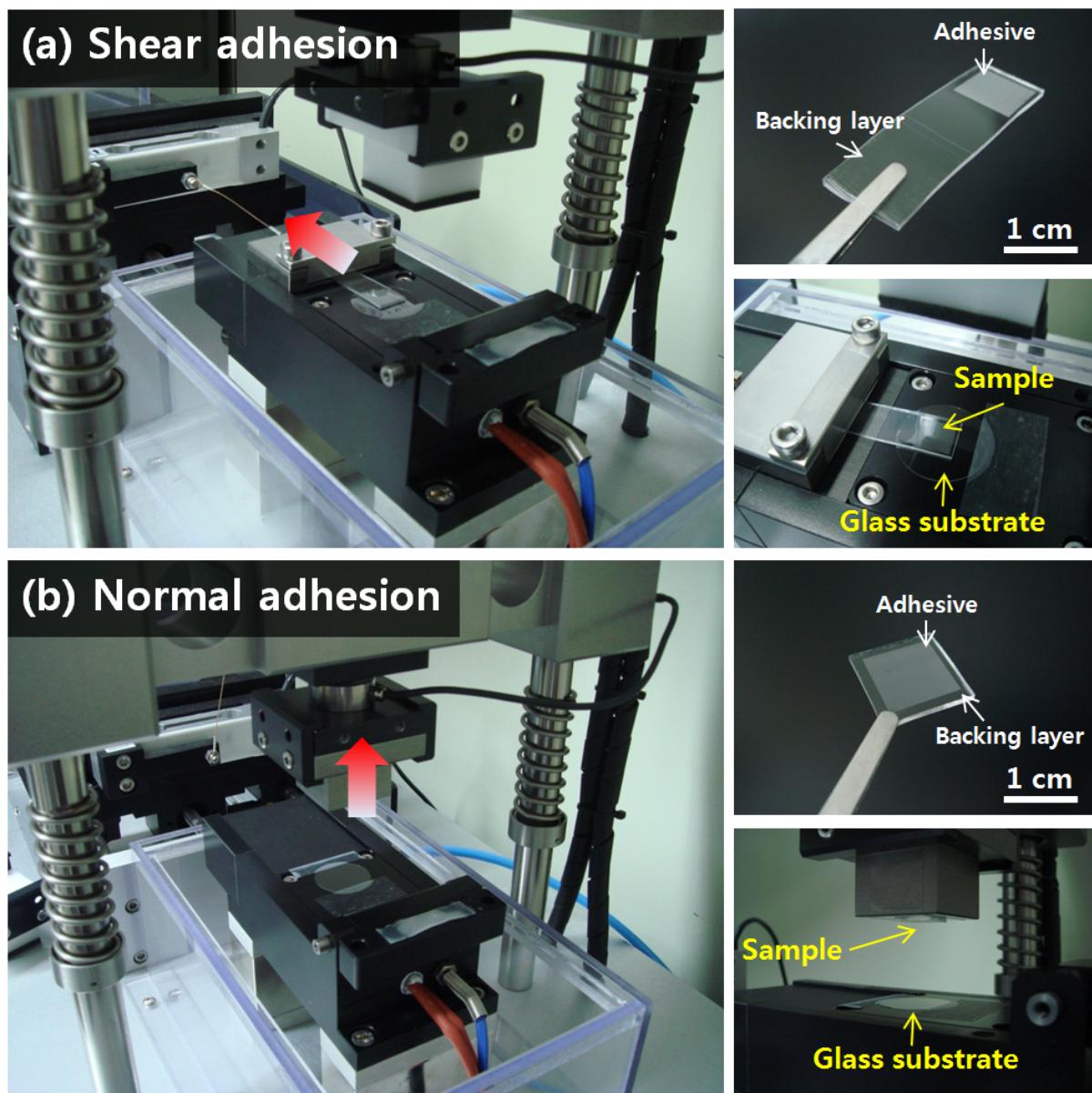


Fig S2. Optical images of the custom-built equipment used in our experiment for adhesion test: (a) shear adhesion and (b) normal adhesion. The sample is 1 mm thick with a patterned area of $1 \times 1 \text{ cm}^2$.

Detailed derivation of the displacement V of micropillars using beam deflection theory

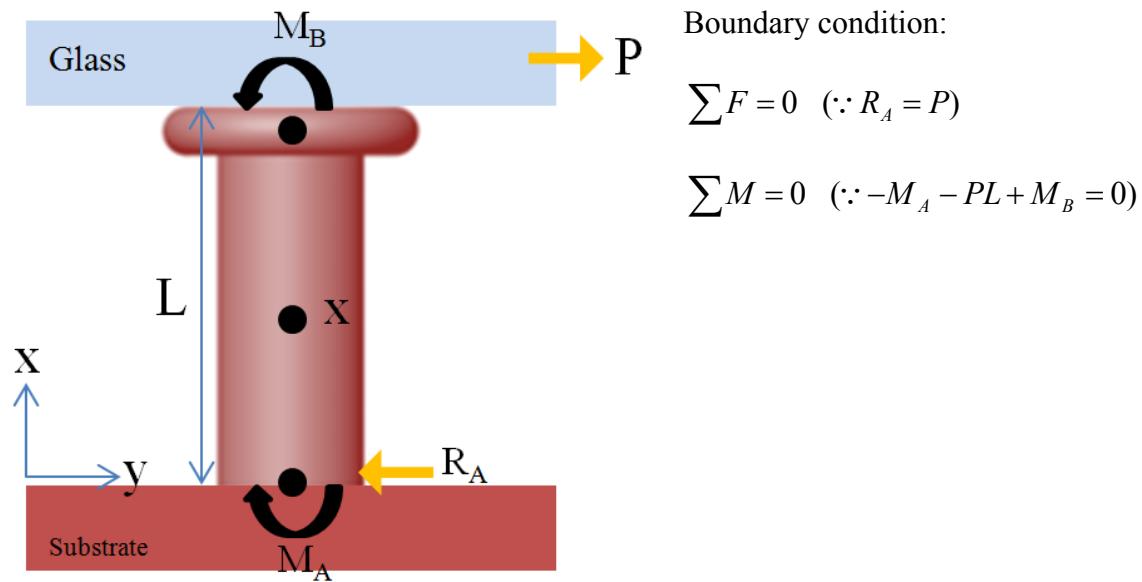


Fig S3. Geometric description of micropillar.

The above expression for the bending moment can be expressed into a second-order differential equation, yielding

$$\frac{d^2v}{dx^2} = \frac{M_{(x)}}{EI} \quad (S1)$$

$$EI \frac{d^2v}{dx^2} = M_{(x)} = M_a + R_a x \quad (S2)$$

$$EI \frac{dv}{dx} = M_a x + \frac{1}{2} R_a x^2 + C_1 \quad (S3)$$

$$EI v = \frac{1}{2} M_a x^2 + \frac{1}{6} R_a x^3 + C_1 + C_2 \quad (S4)$$

$$C_1 = 0, \because x = 0, \frac{dv}{dx} = 0 \quad (S5)$$

$$C_2 = 0, \because x = 0, v = 0 \quad (S6)$$

Then, the deflection v at the tip is given by

$$v = \frac{1}{EI} \left(\frac{1}{2} M_a x^2 + \frac{1}{6} R_A x^3 \right) \quad (S7)$$

$$v_{(x=L)} = \frac{1}{EI} \left(\frac{1}{2} M_a L^2 + \frac{1}{6} R_A L^3 \right) \quad (S8)$$

$$v_{(x=L)} = \frac{1}{EI} \left(-\frac{1}{4} PL^3 + \frac{1}{6} PL^3 \right) \quad \because M_a = -\frac{P}{2}L, R_A = P \quad (S9)$$

$$Av_{(x=L)} = \frac{1}{EI} \left(-\frac{1}{12} PL^3 \right) = -\frac{PL^3}{12EI} \quad (S10)$$