

Supplementary Information to “Intrinsic curvature determines the crinkled edges of “crenellated disks”.”

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A. Total free energy

For a single surface of revolution terminated by two space curves, in terms of the angles α , β_i , and ϕ_i , and the differential geometric quantities defined in the main text, the total free energy is given by

$$F = F_H + F_{edge_1} + F_{edge_2} + F_{\lambda_1} + F_{\lambda_2}, \quad (1)$$

where

$$F_H = \int_{\epsilon}^R dr (\pi + \phi_1 + \phi_2) \left[\frac{\sigma r}{\cos \alpha} + \frac{k}{2r} \sin \alpha \tan \alpha + \frac{k}{2} r \cos \alpha \left(\frac{d\alpha}{dr} \right)^2 \right] + (k + \bar{k}) \int_{\epsilon}^R \frac{dr}{r} (\tan \beta_1 + \tan \beta_2) - (k + \bar{k}) \cos \alpha (R) (\pi + \phi_1(R) + \phi_2(R)) + (k + \bar{k}) \cos \alpha (\epsilon) (\pi + \phi_1(\epsilon) + \phi_2(\epsilon)) \quad (2)$$

$$F_{edge_i} = \int_{\epsilon}^R dr \left[\frac{\gamma_i}{\cos \alpha \cos \beta_i} + k_b \frac{\kappa_{g,i}^2 + \kappa_{n,i}^2}{\cos \alpha \cos \beta_i} - h_i \frac{\sin \beta_i}{\cos \alpha} (\kappa_2 - \kappa_1) \right], \quad (3)$$

$$F_{\lambda_i} = \int_{\epsilon}^R dr \lambda_i \left(r \cos \alpha \frac{d\phi_i}{dr} - \tan \beta_i \right). \quad (4)$$

The index of the edges is $i = \{1, 2\}$, ϵ is the cut-off length, which is given by $\epsilon \equiv -R \sin \alpha (R)$ for the catenoid.

B. Euler-Lagrange equations

The variations $\frac{\delta F}{\delta g_j}$, where $g_j = \{\alpha, \beta_1, \beta_2, \phi_1, \phi_2\}$, are equivalent to the Euler-Lagrange (EL) equations. For one independent and several dependent variables, the EL equations are given by [1]

$$\frac{\partial f}{\partial g_j} = \frac{d}{dx} \frac{\partial f}{\partial g'_j} \quad (5)$$

where $f = f(r, g_j, g'_j)$ is the free energy density given by $F = \int dr f(r, g_j, g'_j)$. Primes denote derivatives $\frac{dg_i}{dr}$. The set of EL Equations in Eq. (5) contains ten coupled nonlinear first-order differential equations. Evaluating Eq. (5), these equations are calculated as

$$u_1 \equiv \frac{\partial f}{\partial \alpha'} = \pi k r \cos \alpha \frac{d\alpha}{dr} + 2k_b \kappa_{n,1} \cos \beta_1 + 2k_b \kappa_{n,2} \cos \beta_2 + h_1 \sin \beta_1 + h_2 \sin \beta_2, \quad (6)$$

$$u_2 \equiv \frac{\partial f}{\partial \beta'_1} = 2k_b \kappa_{g,1}, \quad u_3 \equiv \frac{\partial f}{\partial \beta'_2} = 2k_b \kappa_{g,2}, \quad (7)$$

$$u_4 \equiv \frac{\partial f}{\partial \phi'_1} = \lambda_1 r \cos \alpha, \quad u_5 \equiv \frac{\partial f}{\partial \phi'_2} = \lambda_2 r \cos \alpha, \quad (8)$$

$$u'_1 \cos^2 \alpha = \sigma \pi r \sin \alpha + \frac{k \pi \sin \alpha}{2} \left[\frac{2}{r} - \frac{\sin^2 \alpha}{r} - r \cos^2 \alpha \left(\frac{d\alpha}{dr} \right)^2 \right] + \sin \alpha \sec \beta_1 (\gamma_1 + k_b \kappa_{n,1}^2 - k_b \kappa_{g,1}^2) + \sin \alpha \sec \beta_2 (\gamma_2 + k_b \kappa_{n,2}^2 - k_b \kappa_{g,2}^2) + 2k_b \kappa_{n,1} \sec \beta_1 \left(\frac{\cos^2 \alpha \sin^2 \beta_1}{r} - \frac{\sin 2\alpha}{2} \frac{d\alpha}{dr} \cos^2 \beta_1 \right) + 2k_b \kappa_{n,2} \sec \beta_2 \left(\frac{\cos^2 \alpha \sin^2 \beta_2}{r} - \frac{\sin 2\alpha}{2} \frac{d\alpha}{dr} \cos^2 \beta_2 \right) - \frac{1}{r} (h_1 \sin \beta_1 + h_2 \sin \beta_2) - \frac{\sin 2\alpha}{2} (\lambda_1 \tan \beta_1 + \lambda_2 \tan \beta_2), \quad (9)$$

$$\cos \alpha \cos^2 \beta_1 u'_2 = (k + \bar{k}) \frac{\cos \alpha}{r} + \gamma_1 \sin \beta_1 - \lambda_1 \cos \alpha + k_b \sin \beta_1 (\kappa_{n,1}^2 - \kappa_{g,1}^2) + \frac{2k_b}{r} \kappa_{g,1} \cos \alpha + (4k_b \kappa_{n,1} \cos \beta_1 - h_1 \cos \beta_1 \cot \beta_1) \tau_{g,1}, \quad (10)$$

$$\begin{aligned} \cos \alpha \cos^2 \beta_2 u'_3 &= (k + \bar{k}) \frac{\cos \alpha}{r} + \gamma_2 \sin \beta_2 - \lambda_2 \cos \alpha \\ &+ k_b \sin \beta_2 (\kappa_{n,2}^2 - \kappa_{g,2}^2) + \frac{2k_b}{r} \kappa_{g,2} \cos \alpha \\ &+ (4k_b \kappa_{n,2} \cos \beta_2 - h_2 \cos \beta_2 \cot \beta_2) \tau_{g,2}, \end{aligned} \quad (11)$$

$$u'_4 = u'_5 = \frac{\sigma r}{\cos \alpha} + \frac{k}{2r} \sin \alpha \tan \alpha + \frac{k}{2} r \cos \alpha \left(\frac{d\alpha}{dr} \right)^2. \quad (12)$$

In Eq. (9), the two constraints $r \cos \alpha \frac{d\phi_1}{dr} = \tan \beta_i$ are used. Based on Eqs. (8) and (12), we conclude that $\lambda \equiv \lambda_1 = \lambda_2$. Then, the nine unknowns to be solved are $\alpha, \alpha', \beta_1, \beta'_1, \beta_2, \beta'_2, \phi_1, \phi_2, \lambda$.

Note that we neglect the contribution of the variations $\frac{\delta F}{\delta \phi_i}$ to the surface and edge deformations, as explained in the main text. Therefore, the structure in our approximation is governed solely by $\alpha, \alpha', \beta_1, \beta'_1, \beta_2, \beta'_2$. In the case of the minimal surface, since α and α' are calculated analytically (see main text), the equations governing β_1, β'_1 and β_2, β'_2 are decoupled from each other.

C. Boundary conditions

The torque-free boundary conditions are given by Eqs. (6), (7), and (8) being equal to zero [1]. Suf-

ficiently away from the rotation axis of the surface, in 2D membrane limit, $\alpha = 0, \alpha' = 0$, and $\alpha'' = 0$. Then, $\kappa_{n,i} = 0$. Plugging in these results to Eq. (9), we find that $\sin \beta_i = A_i/r$. This rather expected result applies to a straight line in polar coordinates, where the shortest distance between the origin and the straight line is A_i (or, the in-plane protrusion amplitude). When $h_i = 0$ as in the achiral limit, then the same relation still holds, and this time the torque-free condition $\frac{\partial f}{\partial \alpha'} = 0$ is satisfied. The geodesic curvature $\kappa_{g,i}$ of a straight line vanishes in 2D, hence $\frac{\partial f}{\partial \beta'_i} = 0$. In the 2D membrane limit λ must be zero. This is best seen when a curve with the free energy given in Eq. (3) is minimized on a plane. The resulting EL equations are independent of ϕ_i , then $\lambda = 0$. Hence $\frac{\partial f}{\partial \phi'_i} = 0$, away from the rotation axis of the nonplanar surface. Plugging in these results into Eqs. (10) and (11), we find that $k + \bar{k} = \gamma_1 A_1 = \gamma_2 A_2$. For a minimal surface, k does not contribute to this equation.

At the cusp, ideally, the boundary conditions are $\alpha = -\pi/2$ and $\beta_i = 0$ (again, we ignore $\frac{\delta F}{\delta \phi_i}$ dependence of the structure). In the case of the minimal surface, since $\epsilon \approx 10^{-2} R$, we take $\alpha = 0.95$ which nearly corresponds to a 70° slope. This slope is steep enough as evidenced in Fig. 3(a) in the main text.

[1] Arfken G., Weber H. *Mathematical Methods for Physicists, Sixth Edition* (Elsevier Inc., 2005).